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Numerical Analysis

A residual based a posteriori estimator for the reaction-diffusion problem

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Abstract

A residual based a posteriori estimator for the reaction-diffusion problem is introduced. We show that the estimator gives both an upper and a lower bound to error. Numerical results are presented. *To cite this article: M. Juntunen, R. Stenberg, C. R. Acad. Sci. Paris, Ser. I 347 (2009).*

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Résumé

Un estimateur d'erreur de type résiduel pour la probleme de réaction-diffusion. Nous preséntons une estimateur a posteriori de la probleme de réaction-diffusion. Nous montrons que l'estimateur donne à la fois une borne supérieure et une borne inférieure de l'erreur. Quelques résultats numériques sont présenté. *Pour citer cet article : M. Juntunen, R. Stenberg, C. R. Acad. Sci. Paris, Ser. I 347 (2009).*

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1. Introduction

We consider the finite element approximation of the reaction-diffusion problem

$$-\varepsilon^2 \Delta u + u = f \quad \text{in } \Omega \quad \text{and} \quad u = 0 \quad \text{on } \partial \Omega, \tag{1}$$

with the parameter $\varepsilon > 0$. For $\varepsilon \gtrsim 1$ the problem is a standard elliptic equation. We are, however, interested in the case of a "small" $\varepsilon \ll 1$. In this case, the problem is a singularly perturbed problem, and the question is how to incorporate the effect of ε into the finite element a posteriori analysis. The problem has been studied for example in [4,1]. Here we introduce and analyze an alternative a posteriori estimator. In [2], this is extended to the Brinkman equations modeling flow in porous media.

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2. The a posteriori error estimate

Let $\Omega \subset \mathbb{R}^n$ be a domain with a polygonal or a polyhedral boundary $\partial \Omega$. We assume a shape regular triangular/tetrahedral partitioning C_h of the domain Ω . With h_K we denote the diameter of $K \in C_h$ and we let $h = \max h_K$. With \mathcal{E}_h we denote the internal edges (faces in 3D) of \mathcal{C}_h . The constant *C* is a generic constant independent of the mesh size and problem parameter ε .

Defining the bilinear form

$$\mathcal{A}(u,v) = \varepsilon^2 (\nabla u, \nabla v) + (u,v), \tag{2}$$

the weak form of the problem is: find $u \in V$ such that

$$\mathcal{A}(u,v) = (f,v) \quad \forall v \in H_0^1(\Omega).$$
(3)

Defining $V_h = \{v \in H_0^1(\Omega) \mid v_{|K} \in P_k(K) \forall K \in C_h\}$, the finite element method is: find $u_h \in V_h$ such that

$$\mathcal{A}(u_h, v) = (f, v) \quad \forall v \in V_h.$$
(4)

The natural energy norm is

$$\|v\|_{\varepsilon}^{2} = \varepsilon^{2} \|\nabla v\|_{0}^{2} + \|v\|_{0}^{2}, \tag{5}$$

and the finite element solution is the best approximation with respect to this norm

$$\|u - u_h\|_{\varepsilon} = \inf_{v \in V_h} \|u - v\|_{\varepsilon}.$$
(6)

In general, the problem has a boundary layer of the form $e^{-d/\varepsilon}$, where d is the distance from the boundary. Hence, even for a smooth load f, a uniform mesh will only lead to the following estimate:

$$\|u - u_h\|_{\varepsilon} \leqslant C\sqrt{h} \tag{7}$$

uniformly valid with respect to ε . For a smooth solution the estimate obtained is

$$\|u - u_h\|_{\varepsilon} \leqslant C(\varepsilon h^k + h^{k+1}).$$
(8)

To improve the convergence, adaptive mesh refinement is natural. Here, we introduce a novel residual based a posteriori estimator. The elementwise estimator is defined as

$$E_K(u_h)^2 = \frac{h_K^2}{\varepsilon^2 + h_K^2} \left\| \varepsilon^2 \Delta u_h - u_h + f \right\|_{0,K}^2 + \frac{h_K}{\varepsilon^2 + h_K^2} \left\| \left[\varepsilon^2 \partial_n u_h \right] \right\|_{0,\partial K \cap \mathcal{E}_h}^2$$
(9)

and the global estimator is

$$\eta = \left(\sum_{K \in \mathcal{C}_h} E_K(u_h)^2\right)^{1/2}.$$
(10)

Above $\llbracket \cdot \rrbracket$ denotes the jump and ∂_n denotes the normal derivative.

If $\varepsilon \gtrsim 1$, the elementwise estimator recovers the usual estimator for second order elliptic equations

$$E_K(u_h)^2 \approx h_K^2 \left\| \varepsilon^2 \Delta u_h - u_h + f \right\|_{0,K}^2 + h_K \left\| \left\| \varepsilon^2 \partial_n u_h \right\| \right\|_{0,\partial K \cap \mathcal{E}_h}^2$$

On the other hand, in the limit $\varepsilon \to 0$ (or $\varepsilon \ll h$), when the FE solution is the L^2 -projection of the loading, we have $E_K(u_h)^2 \approx ||-u_h + f||_{0,K}^2$.

For our analysis we will need a saturation assumption. The partitioning C_h is refined into $C_{h/2}$ by dividing each triangle/tetrahedron K into four/eight elements with mesh size $h_K/2$. By $u_{h/2} \in V_{h/2}$ we denote the finite element solution on the refined mesh.

Assumption 2.1. There exists a positive constant $\beta < 1$ such that

$$\|u - u_{h/2}\|_{\varepsilon} \leq \beta \|u - u_h\|_{\varepsilon}.$$
(11)

The main result is the following theorem:

Theorem 2.2. Let Assumption 2.1 hold. Then there exists C > 0 such that

$$\|u - u_h\|_{\varepsilon} \leqslant C\eta. \tag{12}$$

Proof. By the triangle inequality the saturation assumption gives

$$\|u-u_h\|_{\varepsilon} \leqslant \frac{C}{1-\beta} \big(\|u_{h/2}-u_h\|_{\varepsilon}\big). \tag{13}$$

Next, with $v = (u_{h/2} - u_h) / ||u_{h/2} - u_h||_{\varepsilon}$, we have

$$\|u_{h/2} - u_h\|_{\varepsilon} = \mathcal{A}(u_{h/2} - u_h, v) \tag{14}$$

and $||v||_{\varepsilon} = 1$. Let $\tilde{v} \in V_h$ be the Lagrange interpolant of v. Since both v and \tilde{v} are in the finite element spaces, scaling arguments give

$$\left(\sum_{K \in \mathcal{C}_{h/2}} \left(\frac{\varepsilon + h_K}{h_K}\right)^2 \|v - \tilde{v}\|_{0,K}^2\right)^{1/2} \leqslant C \left(\sum_{K \in \mathcal{C}_{h/2}} \left(\varepsilon^2 \|\nabla v\|_{0,K}^2 + \|v\|_{0,K}^2\right)\right)^{1/2} = C \|v\|_{\varepsilon} = C \tag{15}$$

and

$$\left(\sum_{K \in \mathcal{C}_{h/2}} \frac{\varepsilon^2 + h_K^2}{h_K} \|v - \tilde{v}\|_{0,\partial K}^2\right)^{1/2} \leqslant C \left(\sum_{K \in \mathcal{C}_{h/2}} \frac{\varepsilon^2 + h_K^2}{h_K} h_K^{-1} \|v - \tilde{v}\|_{0,K}^2\right)^{1/2} \\
= C \left(\sum_{K \in \mathcal{C}_{h/2}} \left(\frac{\varepsilon^2}{h_K^2} + 1\right) \|v - \tilde{v}\|_{0,K}^2\right)^{1/2} \leqslant C \left(\sum_{K \in \mathcal{C}_{h/2}} \left(\varepsilon^2 \|\nabla v\|_{0,K}^2 + \|v\|_{0,K}^2\right)\right)^{1/2} = C \|v\|_{\varepsilon} = C.$$
(16)

Since it holds $\mathcal{A}(u_{h/2} - u_h, \tilde{v}) = 0$, we have

$$\mathcal{A}(u_{h/2} - u_h, v) = \mathcal{A}(u_{h/2} - u_h, v - \tilde{v}).$$

$$\tag{17}$$

Using the fact that $u_{h/2}$ satisfies

 $\mathcal{A}(u_{h/2}, v - \tilde{v}) = (f, v - \tilde{v})$ (18)

and integrating by parts, we get

$$\mathcal{A}(u_{h/2} - u_h, v - \tilde{v}) = (f, v - \tilde{v}) - \varepsilon^2 (\nabla u_h, \nabla (v - \tilde{v})) - (u_h, v - \tilde{v})$$

=
$$\sum_{K \in \mathcal{C}_{h/2}} \{ (\varepsilon^2 \Delta u_h - u_h + f, v - \tilde{v})_K + \varepsilon^2 \langle \partial_n u_h, v - \tilde{v} \rangle_{\partial K \cap \mathcal{E}_{h/2}} \}.$$
 (19)

Using Schwartz inequality and the estimates (15)–(16) we then obtain

$$\mathcal{A}(u_{h/2} - u_h, v - \tilde{v}) \leqslant C\eta. \qquad \Box \tag{20}$$

The a posteriori upper bound η is also a lower bound to the error. In this sense the estimator is sharp. The proof of the following theorem uses classical techniques, see [3]:

Theorem 2.3. Let $f_h \in V_h$ be an approximation of the load f. Then there exist C > 0 such that

$$\eta^{2} \leqslant C \bigg\{ \|u - u_{h}\|_{\varepsilon}^{2} + \sum_{K \in \mathcal{C}_{h}} \bigg(\frac{h_{K}^{2}}{\varepsilon^{2} + h_{K}^{2}} \|f - f_{h}\|_{0,K}^{2} \bigg) \bigg\}.$$
(21)



Fig. 1. Upper panels: Convergence for uniform and adaptive meshes for parameter values $\varepsilon = 0.05$ and $\varepsilon = 0.01$. Lower panels: First three meshes of the adaptive scheme using linear elements and parameter value $\epsilon = 0.05$.

3. Numerical results

For the computations we choose the unit square $\Omega = (0, 1) \times (0, 1)$ and a unit load f = 1. For the number of degrees of freedom N, the uniform estimate (7) and the asymptotic estimate (8) become

$$||u - u_h||_{\varepsilon} \leq CN^{-0.25}$$
 and $||u - u_h||_{\varepsilon} \leq C(\varepsilon N^{-k/2} + N^{-(k+1)/2}),$ (22)

respectively. In Fig. 1 this behavior is seen for linear and quadratic elements (k = 1, 2).

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