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A Hardy type inequality for $W_0^{2,1}(\Omega)$ functions*Une inégalité de type Hardy pour les fonctions de $W_0^{2,1}(\Omega)$* Hernán Castro^a, Juan Dávila^{b,1}, Hui Wang^{a,c,2}^a Department of Mathematics, Rutgers University, 110 Frelinghuysen Road, Piscataway, NJ 08854, USA^b Departamento de Ingeniería Matemática and Centro de Modelamiento Matemático (UMI 2807 CNRS), Universidad de Chile, Casilla 170 Correo 3, Santiago, Chile^c Department of Mathematics, Technion, Israel Institute of Technology, 32000 Haifa, Israel

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ABSTRACT

We consider functions $u \in W_0^{2,1}(\Omega)$, where $\Omega \subset \mathbb{R}^N$ is a smooth bounded domain. We prove that $\frac{u(x)}{d(x)} \in W_0^{1,1}(\Omega)$ with

$$\left\| \nabla \left(\frac{u(x)}{d(x)} \right) \right\|_{L^1(\Omega)} \leq C \|u\|_{W^{2,1}(\Omega)},$$

where d is a smooth positive function which coincides with $\text{dist}(x, \partial\Omega)$ near $\partial\Omega$ and C is a constant depending only on d and Ω .

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R É S U M É

Nous considérons des fonctions $u \in W_0^{2,1}(\Omega)$, où $\Omega \subset \mathbb{R}^N$ est un domaine régulier borné. Nous prouvons que $\frac{u(x)}{d(x)} \in W_0^{1,1}(\Omega)$ avec

$$\left\| \nabla \left(\frac{u(x)}{d(x)} \right) \right\|_{L^1(\Omega)} \leq C \|u\|_{W^{2,1}(\Omega)},$$

où d est une fonction régulière positive qui coïncide avec $\text{dist}(x, \partial\Omega)$ près de $\partial\Omega$ et C est une constante ne dépendant que de d et Ω .

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1. Introduction

In [4], the following one-dimensional Hardy type inequality was proved (see Theorem 1.2 in [4]): suppose that $u \in W^{2,1}(0, 1)$ satisfies $u(0) = u'(0) = 0$, then $\frac{u(x)}{x} \in W^{1,1}(0, 1)$ with $\frac{u(x)}{x}|_{x=0} = 0$ and

$$\left\| \left(\frac{u(x)}{x} \right)' \right\|_{L^1(0,1)} \leq \|u''\|_{L^1(0,1)}. \quad (1)$$

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As explained in [4], this inequality is somehow unexpected because one can construct a function $u \in W^{2,1}(0, 1)$ such that $u(0) = u'(0) = 0$ and that neither $\frac{u'(x)}{x}$ nor $\frac{u(x)}{x^2}$ belong to $L^1(0, 1)$; however, as (1) shows, for such function u , the difference $\frac{u'(x)}{x} - \frac{u(x)}{x^2} = \left(\frac{u(x)}{x}\right)'$ is in fact an L^1 function, reflecting a “magical” cancellation of the non-integrable terms.

The purpose of this work is to present the complete analog of the estimate (1) in dimension $N \geq 2$. We have the following:

Theorem 1.1. *Let Ω be a bounded domain in \mathbb{R}^N with smooth boundary $\partial\Omega$. Given $x \in \Omega$, we denote by $\delta(x)$ the distance from x to the boundary $\partial\Omega$. Let $d : \Omega \rightarrow (0, +\infty)$ be a smooth function such that $d(x) = \delta(x)$ near $\partial\Omega$. Then for every $u \in W_0^{2,1}(\Omega)$, we have $\frac{u(x)}{d(x)} \in W_0^{1,1}(\Omega)$ with*

$$\left\| \nabla \left(\frac{u(x)}{d(x)} \right) \right\|_{L^1(\Omega)} \leq C \|u\|_{W^{2,1}(\Omega)}, \quad (2)$$

where $C > 0$ is a constant depending only on d and Ω .

In Section 2 we present the notation and in Section 3 we sketch the proof of Theorem 1.1.

2. Notation and preliminaries

Throughout this work, we denote $\tilde{y} = (y_1, \dots, y_{N-1})$, $\mathbb{R}_+^N := \{y_N > 0\}$, and $B_r^N := \{y \in \mathbb{R}^N : |y| < r\}$; $\Omega \subset \mathbb{R}^N$ is always a bounded domain with smooth boundary $\partial\Omega$ and we denote by $\delta(x) := \text{dist}(x, \partial\Omega)$. Using Lemma 14.16 in [6], one can construct a smooth change of coordinates $\Phi : B_r^{N-1} \times (-\epsilon_0, \epsilon_0) \rightarrow \mathbb{R}^N$, defined by

$$\Phi(\tilde{y}, t) := \tilde{\Phi}(\tilde{y}) + y_N \nu_{\partial\Omega}(\tilde{\Phi}(\tilde{y})), \quad (3)$$

where $\nu_{\partial\Omega}(z)$ denotes the unit inward normal vector at $z \in \partial\Omega$ and $\tilde{\Phi} : B_r^{N-1} \rightarrow \mathcal{V}(\tilde{x}_0)$ is a smooth coordinate chart at $\tilde{x}_0 \in \partial\Omega$ (with $\mathcal{V}(\tilde{x}_0)$ denoting a neighborhood of \tilde{x}_0 in $\partial\Omega$). If we denote

$$\mathcal{N}(\tilde{x}_0) := \Phi(B_r^{N-1} \times (-\epsilon_0, \epsilon_0)), \quad (4)$$

then the map $\Phi|_{B_r^{N-1} \times (0, \epsilon_0)}$ is a diffeomorphism and we denote

$$\mathcal{N}_+(\tilde{x}_0) := \{x \in \Omega_{\epsilon_0} : y_x \in \mathcal{V}(\tilde{x}_0)\} = \Phi(B_r^{N-1} \times (0, \epsilon_0)). \quad (5)$$

This type of coordinates are sometimes called *flow coordinates* (see e.g. [3] and [7]).

3. The proof of the theorem

The key ingredient in the proof is the following lemma:

Lemma 3.1. *Suppose $u \in C_0^\infty(\mathbb{R}_+^N)$. Then for all $i = 1, \dots, N$ we have*

$$\left\| \partial_i \left(\frac{u(y)}{y_N} \right) \right\|_{L^1(\mathbb{R}_+^N)} \leq C \|u\|_{W^{2,1}(\mathbb{R}_+^N)}.$$

Proof. We first notice that when $i = N$, the result is essentially contained in the proof of Theorem 1.2 of [4] when $j = 0$, $k = 1$ and $m = 2$. We refer the reader to [4] for the details. When $1 \leq i \leq N - 1$, define $v(x) = u(\Psi(x))$ where $\Psi(x_1, \dots, x_i, \dots, x_N) = (x_1, \dots, x_i + x_N, \dots, x_N)$. We have

$$\frac{1}{x_N} \frac{\partial u}{\partial y_i}(\Psi(x)) = \frac{\partial}{\partial x_N} \left(\frac{v(x)}{x_N} \right) - \frac{\partial}{\partial y_N} \left(\frac{u(y)}{y_N} \right) \Big|_{y=\Psi(x)}.$$

Therefore the estimate is reduced to the case $i = N$. \square

Next we use Lemma 3.1 together with the straightening of the boundary given by Φ in Section 2 to obtain

Lemma 3.2. *Let $\tilde{x}_0 \in \partial\Omega$ and $\mathcal{N}_+(\tilde{x}_0)$ be given by (5). Suppose $u \in C_0^\infty(\mathcal{N}_+(\tilde{x}_0))$. Then for all $i = 1, \dots, N$ we have*

$$\left\| \partial_i \left(\frac{u(x)}{\delta(x)} \right) \right\|_{L^1(\mathcal{N}_+(\tilde{x}_0))} \leq C \|u\|_{W^{2,1}(\mathcal{N}_+(\tilde{x}_0))}.$$

Proof. Let $v(\tilde{y}, y_N) := u(\Phi(\tilde{y}, y_N))$. Using the fact that Φ is a smooth diffeomorphism gives

$$\int_{\mathcal{N}_+(\tilde{x}_0)} \left| \partial_i \left(\frac{u(x)}{\delta(x)} \right) \right| dx \leq C \sum_{j=1}^N \int_{B_r^{N-1}} \int_0^{\epsilon_0} \left| \partial_j \left(\frac{v(\tilde{y}, y_N)}{y_N} \right) \right| dy_N d\tilde{y}. \tag{6}$$

Since $v \in C_0^\infty(B_r^{N-1} \times (0, \epsilon_0)) \subset C_0^\infty(\mathbb{R}_+^N)$, we can apply Lemma 3.1 and obtain

$$\int_{B_r^{N-1}} \int_0^{\epsilon_0} \left| \partial_j \left(\frac{v(\tilde{y}, y_N)}{y_N} \right) \right| dy_N d\tilde{y} \leq C \|v\|_{W^{2,1}(B_r^{N-1} \times (0, \epsilon_0))}.$$

Notice that by the chain rule and the fact that Φ is a smooth diffeomorphism, we get

$$\|v\|_{W^{2,1}(B_r^{N-1} \times (0, \epsilon_0))} \leq C \|u\|_{W^{2,1}(\mathcal{N}_+(\tilde{x}_0))}. \quad \square$$

Proof of Theorem 1.1. Applying Lemma 3.2 and a partition of unity (see e.g. Lemma 9.3 in [2] and Theorem 3.15 in [1]), one can obtain that

$$\left\| \partial_i \left(\frac{u(x)}{\delta(x)} \right) \right\|_{L^1(\Omega)} \leq C \|u\|_{W^{2,1}(\Omega)},$$

for $u \in C_0^\infty(\Omega)$ and $i = 1, \dots, N$. Then one can complete the proof of Theorem 1.1 using a standard density argument. \square

Remark 1. In fact, we have a full generalization of Theorem 1.1 for functions in $W_0^{m,1}(\Omega)$ for all the integers $m \geq 2$, which is presented in [5].

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