# A Carleman estimate for the two dimensional heat equation with mixed boundary conditions 

# Inégalité de Carleman pour l'équation de la chaleur avec conditions mixtes en dimension deux 

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#### Abstract

It is well known that in a regular domain, the solutions of the Laplace equation with mixed boundary conditions can present a singular part. In this work, we prove a Carleman estimate for the two dimensional domain heat equation in presence of these singularities. © 2013 Académie des sciences. Published by Elsevier Masson SAS. All rights reserved. R É S U M É Il est bien connu que dans un ouvert régulier, les solutions du problème mêlé pour l'équation de Laplace présentent des singularités. Le but de ce travail est d'établir une inégalité de Carleman pour l'équation de la chaleur en dimension deux en présence de ces singularités.


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## 1. Introduction

Let $\Omega$ be a bounded open connected set of $\mathbb{R}^{2}$ with $C^{2}$ boundary $\Gamma=\partial \Omega$. Let $\Gamma_{D}$ and $\Gamma_{N}$ be two subsets of $\Gamma$ such that: $\Gamma=\Gamma_{D} \cup \Gamma_{N}, \Gamma_{D} \cap \Gamma_{N}=\emptyset$ and $\bar{\Gamma}_{D} \cap \bar{\Gamma}_{N}=\left\{S_{1}, S_{2}\right\}$. Let $\omega \subset \Omega$ be a non-empty open subset. For $T>0$, we set $Q_{T}=\Omega \times(0, T), \Sigma_{D T}=\Gamma_{D} \times(0, T), \Sigma_{N T}=\Gamma_{N} \times(0, T)$ and $\Sigma_{T}=\Gamma \times(0, T)$. We will denote by $v(x)$ the outward unit normal to $\Omega$ at $x \in \Gamma$. We consider the following mixed boundary value problem:

$$
\begin{cases}-\Delta u=f & \text { in } \Omega  \tag{1}\\ u=0 & \text { on } \Gamma_{D} \\ \frac{\partial u}{\partial v}=0 & \text { on } \Gamma_{N}\end{cases}
$$

where $f$ is given in $L^{2}(\Omega)$ and $\frac{\partial u}{\partial \nu}$ is the normal derivative of $u$. It is well known, see [8], that the solution of (1) is not in $H^{2}(\Omega)$, and more precisely the solution, according to [7] is given by:

$$
\begin{equation*}
u(r, \theta)=u_{R}(r, \theta)+C_{1} \sqrt{r_{1}} \sin \frac{\theta_{1}}{2} \chi_{1}+C_{2} \sqrt{r_{2}} \cos \frac{\theta_{2}}{2} \chi_{2} \tag{2}
\end{equation*}
$$

[^0]where $u_{R} \in H^{2}(\Omega)$ is the regular part, $\left(r_{j}, \theta_{j}\right)$ are the local polar coordinates at $S_{j}, C_{j}$ are real constants, $\chi_{j}$ are cut-off functions such that $0 \leqslant \chi_{j} \leqslant 1$ and $\chi_{j}=1$ on a neighborhood of $S_{j}$.

The aim of this note is to establish a Carleman estimate for the following problem:

$$
\begin{cases}\partial_{t} u-\Delta u=f & \text { in } Q_{T}  \tag{3}\\ u=0 & \text { on } \Sigma_{D T} \\ \frac{\partial u}{\partial v}=0 & \text { on } \Sigma_{N T} \\ u(\cdot, 0)=u_{0} & \text { in } \Omega\end{cases}
$$

where $u_{0} \in L^{2}(\Omega)$ and $f \in L^{2}\left(Q_{T}\right)$.
Carleman estimates have many applications varying from the quantification of the unique continuation problems, inverse problems to stabilization and control theory. These applications are the motivation to prove a suitable Carleman estimate for our problem. To the best of our knowledge, very few results on Carleman estimates in the presence of singularities have been established. We cite [2] for the Laplace equation for a domain with a corner, [1] for the heat equation in a singular domain and [3] for the wave equation with mixed conditions using microlocal approach. Our methodology here is in a similar spirit of [1,4-6].

In order to get well-possedness for (3), we define the following spaces:

$$
V=\left\{u \in H^{1}(\Omega) ; u=0 \text { on } \Gamma_{D}\right\}
$$

and

$$
\begin{aligned}
D(-\Delta) & =\left\{u \in V ; \Delta u \in L^{2}(\Omega) ; \frac{\partial u}{\partial v}=0 \text { on } \Gamma_{N}\right\} \\
& =\left\{u \in V \cap H^{2}(\Omega) ; \frac{\partial u}{\partial v}=0 \text { on } \Gamma_{N}\right\} \oplus \operatorname{span}\left\{r^{\frac{1}{2}} \sin \frac{\theta}{2}, r^{\frac{1}{2}} \cos \frac{\theta}{2}\right\}
\end{aligned}
$$

Problem (3) has a unique solution $u \in C\left([0, T] ; L^{2}(\Omega)\right) \cap C((0, T) ; D(-\Delta)) \cap C^{1}\left((0, T) ; L^{2}(\Omega)\right)$. Note that, even for very smooth data $f$ and $u_{0}$, the solution of (3) is not regular near $S_{1}$ and $S_{2}$.

## 2. Main result

In the following, for $k=0,1$, we set:

$$
\begin{equation*}
\xi_{k}(x, t)=\frac{e^{(-1)^{k} \lambda \beta(x)}}{t(T-t)}, \quad \alpha_{k}(x, t)=\frac{e^{2 \lambda\|\beta\|_{\infty}}-e^{(-1)^{k} \lambda \beta(x)}}{t(T-t)} \tag{4}
\end{equation*}
$$

Here, $\lambda \geqslant 1$ is a parameter and $\beta=\beta(x)$ is a function satisfying:

$$
\begin{equation*}
\beta \in C^{2}(\bar{\Omega}), \quad \beta(x)>0 \quad \text { in } \Omega, \quad \beta(x)=0 \quad \text { on } \partial \Omega, \quad|\nabla \beta|>0 \quad \text { on } \overline{\Omega \backslash \omega^{\prime}}, \tag{5}
\end{equation*}
$$

where $\omega^{\prime} \Subset \omega$ is a non-empty open set. The existence of $\beta$ satisfying (5) is proved in [6].
We state our main result, for $\alpha=\alpha_{0}$ and $\xi=\xi_{0}$ :
Theorem 2.1. Given $f \in L^{2}\left(Q_{T}\right)$ and $u_{0} \in L^{2}(\Omega)$. There exist $s_{0}, \lambda_{0}$ and $C=C(\Omega, \omega)$ such that for any $s>s_{0}, \lambda>\lambda_{0}$ the solution of (3) satisfies:

$$
\begin{equation*}
I\left(u, \xi_{0}, \alpha_{0}, Q_{T}\right) \leqslant C\left(\int_{Q_{T}} e^{-2 s \alpha_{0}}|f|^{2} \mathrm{~d} x \mathrm{~d} t+s^{3} \lambda^{4} \int_{\omega \times(0, T)} \xi_{0}^{3} e^{-2 s \alpha_{0}}|u|^{2} \mathrm{~d} x \mathrm{~d} t\right) \tag{6}
\end{equation*}
$$

where

$$
\begin{equation*}
I\left(u, \xi, \alpha, Q_{T}\right)=\int_{Q_{T}} e^{-2 s \alpha}\left((s \xi)^{-1}\left(\left|\partial_{t} u\right|^{2}+|\Delta u|^{2}\right)+s \lambda^{2} \xi|\nabla u|^{2}+s^{3} \lambda^{4} \xi^{3}|u|^{2}\right) \mathrm{d} x \mathrm{~d} t \tag{7}
\end{equation*}
$$

Sketch of the proof. The proof will be given in four steps.
Regularization of the solution: The regularity of the solution $u$ is not sufficient to do some integrations by parts. We then approximate $u$ by a sequence of regular functions $\left(u_{n}\right)$. Spaces $D(-\Delta)$ and $D\left((-\Delta)^{2}\right)$ are dense in $L^{2}(\Omega)$, then for $u_{0} \in L^{2}(\Omega)$ and $f \in L^{2}\left(0, T ; L^{2}(\Omega)\right)$, there exist sequences $\left(u_{n}^{0}\right)_{n} \subset D\left((-\Delta)^{2}\right)$ and $\left(f_{n}\right)_{n} \subset C^{1}(0, T ; D(-\Delta))$ such that $\left(u_{n}^{0}\right)_{n}$ converges to $u_{0}$ in $L^{2}(\Omega)$ and $\left(f_{n}\right)_{n}$ converges to $f$ in $L^{2}\left(0, T ; L^{2}(\Omega)\right)$, then the problem (3) with $f=f_{n}$ and $u_{0}=u_{n}^{0}$ has a unique solution $u_{n} \in C^{2}\left((0, T) ; L^{2}(\Omega)\right) \cap C^{1}([0, T] ; D(-\Delta))$ and we can prove the following lemma:

Lemma 2.1. For $k=0,1$, set $\psi_{n, k}(x, t)=e^{-s \alpha_{k}(x, t)} u_{n}(x, t)$ and $\psi_{k}(x, t)=e^{-s \alpha_{k}(x, t)} u(x, t)$, we have

1. $\left(u_{n}\right)_{n}$ converges to $u$ in $L^{2}(0, T ; V)$,
2. $\left(\Delta \psi_{n, k}\right)_{n}$ converges to $\left(\Delta \psi_{k}\right)$ in $L^{2}\left(Q_{T}\right)$.

In the sequel, and for simplicity, we will drop the index $n$.
Approximation of the domain: To remedy the lack of regularity of the solution near $S_{1}$ and $S_{2}$, we set, for $\varepsilon>0$

$$
\begin{aligned}
& \Omega_{\epsilon}=\Omega \backslash \bigcup_{k=1}^{2} B\left(S_{k}, \varepsilon\right), \quad \partial \Omega_{\varepsilon}=\Gamma_{D}^{\varepsilon} \cup \Gamma_{N}^{\varepsilon} \cup C_{\varepsilon}^{1} \cup C_{\varepsilon}^{2} \\
& Q_{\varepsilon, T}=\Omega_{\varepsilon} \times(0, T), \quad \Sigma_{\varepsilon, T}=\partial \Omega_{\varepsilon} \times(0, T), \quad C_{\varepsilon}^{k}=\partial B\left(S_{k}, \varepsilon\right) \cap \Omega
\end{aligned}
$$

where $B\left(S_{k}, \varepsilon\right)$ is the ball of radius $\varepsilon$ and centred in $S_{k}$.
Derivation of the Carleman estimate: For $k=0,1$, let:

$$
\begin{equation*}
\xi_{k}(x, t)=\frac{e^{(-1)^{k} \lambda \beta(x)}}{t(T-t)}, \quad \alpha_{k}(x, t)=\frac{e^{2 \lambda\|\beta\|_{\infty}}-e^{(-1)^{k} \lambda \beta(x)}}{t(T-t)} \tag{8}
\end{equation*}
$$

we set:

$$
\begin{equation*}
\psi_{k}(x, t)=e^{-s \alpha_{k}(x, t)} u(x, t) \tag{9}
\end{equation*}
$$

and

$$
L \psi_{k}=M_{1} \psi_{k}+M_{2} \psi_{k}=F_{k}
$$

where

$$
\left\{\begin{array}{l}
M_{1} \psi_{k}=2 s \lambda^{2} \xi_{k}|\nabla \beta|^{2} \psi_{k}+2(-1)^{k} s \lambda \xi_{k} \nabla \beta . \nabla \psi_{k}+\partial_{t} \psi_{k} \\
M_{2} \psi_{k}=-s^{2} \lambda^{2}|\nabla \beta|^{2} \xi_{k}^{2} \psi_{k}-\Delta \psi_{k}+s \partial_{t} \alpha_{k} \psi_{k} \\
F_{k}=e^{-s \alpha_{k}} f-(-1)^{k} s \lambda \xi_{k} \Delta \beta \psi_{k}+s \lambda^{2} \xi_{k}|\nabla \beta|^{2} \psi_{k}
\end{array}\right.
$$

$\left(M_{1} \psi_{k}\right)_{i},\left(M_{2} \psi_{k}\right)_{j}$ are respectively the $i$-th and the $j$-th term of $M_{1} \psi_{k}$ and of $M_{2} \psi_{k}$.

$$
\begin{equation*}
\left\|M_{1} \psi_{k}\right\|_{L^{2}\left(Q_{T}\right)}^{2}+\left\|M_{2} \psi_{k}\right\|_{L^{2}\left(Q_{T}\right)}^{2}+2 \sum_{i, j=1}^{3}\left\langle\left(M_{1} \psi_{k}\right)_{i},\left(M_{2} \psi_{k}\right)_{j}\right\rangle_{L^{2}\left(Q_{T}\right)}=\left\|F_{k}\right\|_{L^{2}\left(Q_{T}\right)}^{2} . \tag{10}
\end{equation*}
$$

Using integration by parts in (10), we derive the following inequality:
Lemma 2.2. There exist $s_{0}, \lambda_{0}$ and $C=C(\Omega, \omega)$ such that for any $s>s_{0}, \lambda>\lambda_{0}$,

$$
\begin{equation*}
I\left(\psi_{k}, \xi_{k}, \alpha_{k}, Q_{\varepsilon, T}\right)+J\left(\psi_{k}, \xi_{k}, \alpha_{k}, \Sigma_{\varepsilon, T}\right) \leqslant C\left(\int_{Q_{\varepsilon, T}} e^{-2 s \alpha_{k}}|f|^{2} \mathrm{~d} x \mathrm{~d} t+s^{3} \lambda^{4} \int_{\omega \times(0, T)} \xi_{k}^{3}\left|\psi_{k}\right|^{2} \mathrm{~d} x \mathrm{~d} t\right) \tag{11}
\end{equation*}
$$

where $I\left(\psi_{k}, \xi_{k}, \alpha_{k}, Q_{\varepsilon, T}\right)$ is given by (7) and

$$
\begin{aligned}
J\left(\psi_{k}, \xi_{k}, \alpha_{k}, \Sigma\right)= & 2(-1)^{k+1}\left(s^{3} \lambda^{3} \int_{\Sigma} \xi_{k}^{3}|\nabla \beta|^{2} \nabla \beta . \nu\left|\psi_{k}\right|^{2} \mathrm{~d} \sigma \mathrm{~d} t+(-1)^{k} 2 s \lambda^{2} \int_{\Sigma} \xi_{k} \frac{\partial \psi_{k}}{\partial v}|\nabla \beta|^{2} \psi_{k} \mathrm{~d} \sigma \mathrm{~d} t\right. \\
& +2 s \lambda \int_{\Sigma} \xi_{k}\left(\nabla \beta . \nabla \psi_{k}\right) \frac{\partial \psi_{k}}{\partial v} \mathrm{~d} \sigma \mathrm{~d} t-s \lambda \int_{\Sigma} \xi_{k}\left|\nabla \psi_{k}\right|^{2}(\nabla \beta . \nu) \mathrm{d} \sigma \mathrm{~d} t \\
& \left.+(-1)^{k} \int_{\Sigma} \frac{\partial \psi_{k}}{\partial \nu} \partial_{t} \psi_{k} \mathrm{~d} \sigma \mathrm{~d} t-s^{2} \lambda \int_{\Sigma} \xi \alpha_{t} \nabla \beta \cdot \nu|\psi|^{2} \mathrm{~d} \sigma \mathrm{~d} t\right)
\end{aligned}
$$

and

$$
\begin{equation*}
J\left(\cdot, \cdot, \cdot, \Sigma_{\varepsilon, T}\right)=J\left(\cdot, \cdot, \cdot, \Sigma_{\varepsilon, T}^{D}\right)+J\left(\cdot, \cdot, \cdot, \Sigma_{\varepsilon, T}^{N}\right)+J\left(\cdot, \cdot, \cdot, C_{\varepsilon, T}^{1}\right)+J\left(\cdot, \cdot, \cdot, C_{\varepsilon, T}^{2}\right) \tag{12}
\end{equation*}
$$

Treatment of boundary terms and passing to the limit in $\boldsymbol{\varepsilon}$ : Since $\beta=0$ on $\Gamma$ then $\alpha_{0}=\alpha_{1}, \xi_{0}=\xi_{1}$ and $\psi_{0}=\psi_{1}$, we deduce that:

$$
\psi_{0}=\psi_{1}=0, \quad \frac{\partial \psi_{0}}{\partial v}=\frac{\partial \psi_{1}}{\partial v} \quad \text { on } \Gamma_{D}^{\varepsilon}, \quad \frac{\partial \psi_{0}}{\partial v}=-\frac{\partial \psi_{1}}{\partial v}, \quad\left|\nabla \psi_{0}\right|=\left|\nabla \psi_{1}\right| \quad \text { on } \Gamma_{N}^{\varepsilon},
$$

which implies that:

$$
\begin{equation*}
\sum_{k=0}^{1} J\left(\psi_{k}, \xi_{k}, \alpha_{k}, \Sigma_{\varepsilon, T}^{D}\right)=\sum_{k=0}^{1} J\left(\psi_{k}, \xi_{k}, \alpha_{k}, \Sigma_{\varepsilon, T}^{N}\right)=0 \tag{13}
\end{equation*}
$$

On $C_{\varepsilon}^{l}, l=1,2$, we use the density of $D(-\Delta) \cap C^{1}(\bar{\Omega}) \oplus \operatorname{span}\left\{r^{\frac{1}{2}} \sin \frac{\theta}{2}, r^{\frac{1}{2}} \cos \frac{\theta}{2}\right\}$ in $D(-\Delta)$, this allows us to write $u$ in the form (2) with $u_{R}(\cdot, t) \in C^{1}(\bar{\Omega})$ for all $t \in(0, T)$, which implies that, for any $t \in(0, T)$ :

$$
\psi_{k}(\cdot, t)=O(\sqrt{\varepsilon}) \quad \text { and } \quad\left|\nabla \psi_{k}(\cdot, t)\right|=O\left(\frac{1}{\sqrt{\varepsilon}}\right)
$$

Using the continuity of $\alpha_{k}$ and $\xi_{k}$, one can have:

$$
\begin{equation*}
\lim _{\varepsilon \rightarrow 0} \sum_{k=0}^{1} J\left(\psi_{k}, \xi_{k}, \alpha_{k}, C_{\varepsilon}^{l}\right)=0, \quad l=1,2 \tag{14}
\end{equation*}
$$

Then from (12)-(14), we deduce that:

$$
\lim _{\varepsilon \rightarrow 0} \sum_{k=0}^{1} J\left(\psi_{k}, \xi_{k}, \alpha_{k}, \Sigma_{\varepsilon, T}\right)=0
$$

Finally, by Lebesgue's theorem, we have:

$$
\lim _{\varepsilon \rightarrow 0} \sum_{k=0}^{1} I\left(\psi_{k}, \xi_{k}, \alpha_{k}, Q_{\varepsilon, T}\right)=\sum_{k=0}^{1} I\left(\psi_{k}, \xi_{k}, \alpha_{k}, Q_{T}\right)
$$

To achieve the proof of Theorem 2.1 we use, as in [4,6], the usual technics for Carleman estimates and the fact that

$$
\xi_{1} \leqslant \xi_{0} \quad \text { and } \quad e^{-s \alpha_{1}} \leqslant e^{-s \alpha_{0}}
$$

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