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Partial differential equations, Control theory / Équations aux dérivées partielles, Théorie du contrôle

# A formula for the sum of *n* weak<sup>\*</sup> closed sets in $L^{\infty}$

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**Abstract.** In this note, we derive an equation which describes the closure of a particular set comprising n-valued functions. This result provides an answer to a long standing question for which the particular case n = 2 had been known and used frequently in the optimal control problems.

Keywords. n-valued functions, formulation, weak\* closure, rearrangements, eigenvalues.

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## 1. Introduction

In many optimal control problems, the admissible set is defined as follows

$$A := \left\{ f \in L^{\infty}(D) : f(f-1) = 0, \int_{D} f \, \mathrm{d}x = \alpha \right\}$$
(1)

where *D* is a bounded (measurable) set in  $\mathbb{R}^N$ ,  $\alpha \in (0, |D|)$ , and |D| denotes the Lebesgue measure of *D*, see for example [7]. Henceforth, we identity  $L^{\infty}$  as  $(L^1)^*$ , the dual of  $L^1$ . Then, it is widely known that

$$w^{\star} - \text{closure of } A = \left\{ f \in L^{\infty}(D) : 0 \le f \le 1, \int_{D} f \, \mathrm{d}x = \alpha \right\},$$
(2)

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see Proposition 2.4 in [3]. This latter set is drastically more convenient to work with compared to the former. For example, it is convex and weak<sup>\*</sup> compact in  $L^{\infty}(D)$ , whereas *A* fails to retain either of these two properties.

In this note, we answer a long standing question; mainly, there is an analogy of (2) for n-valued functions. More precisely, we replace the set of  $\{0, 1\}$ -valued functions (verifying the integral constraint  $\int_D f dx = \alpha$ ), i.e. A, by an appropriate set of n-valued functions. A natural generalization of (1) is the following set

$$\widetilde{A} = \left\{ f \in L^{\infty}(D) : (f - \gamma_1)(f - \gamma_2) \cdots (f - \gamma_n) = 0, \int_D f \, \mathrm{d}x = \alpha \right\}.$$

However, a function  $h \in \widetilde{A}$  may not satisfy the condition  $|\{x \in D : f(x) = \gamma_i\}| > 0, i = 1, 2, ..., n$ , which we require, as illustrated by the following example:

**Example.** Let D = (0, 1),  $\alpha = 1$  and  $\gamma_i = i - 1$ , i = 1, 2, 3. Clearly, the set  $\tilde{A}$  contains the following 2-valued and 3-valued controls:

$$f_1 = 2\chi_{(\frac{1}{2},1)}, \quad f_2 = \chi_{(0,\frac{1}{3})} + 2\chi_{(\frac{2}{3},1)}$$

Note that this drawback is irrelevant to *A* due to imposing the condition  $\alpha \in (0, |D|)$ . To overcome this obstacle, we first make the following observation that

$$A = \left\{ \chi_E : E \subseteq D, |E| = \alpha \right\}$$

where  $\chi_E$  denotes the characteristic function of *E*. Furthermore, we make a second observation that

$$\{\chi_E : E \subseteq D, |E| = \alpha\} = \mathscr{R}(\chi_F)$$

where *F* can be any subset of *D* verifying  $|F| = \alpha$ . Here,  $\mathscr{R}(\chi_F)$  denotes the classical rearrangement class generated by  $\chi_F$ . In the following lines, we briefly recall the definition of two functions being rearrangements of each other.

For two (measurable) functions  $f, g: D \to \mathbb{R}$ , we say f and g are rearrangements of each other if

$$\lambda_f(\alpha) = \lambda_g(\alpha) \text{ for all } \alpha \in \mathbb{R},$$

where  $\lambda_f$  (similarly  $\lambda_g$ ) denotes the distribution function of f, i.e.

$$\lambda_f(\alpha) = |\{x \in D : f(x) \ge \alpha\}|.$$

We use the notation  $\mathscr{R}(f)$  to indicate the set of functions defined on *D* which are rearrangements of *f*;  $\mathscr{R}(f)$  is called the rearrangement class generated by *f*. Note that if *f* and *g* are rearrangements of each other, they will generate the same class of rearrangements, i.e.  $\mathscr{R}(f) = \mathscr{R}(g)$ .

Now, for  $c_i \in \mathbb{R}$ , i = 1, 2, ..., n, we introduce the set

$$\mathscr{A} = \left\{ \sum_{i=1}^{n} c_i \chi_{E_i} : E_i \subseteq D, \{E_i\} \text{ are mutually disjoint, } |E_i| = \alpha_i \right\},\$$

where  $\alpha_i > 0$  are prescribed satisfying  $\sum_{i=1}^{n} \alpha_i = |D|$ . Without loss of generality, we suppose  $\{c_i\}$  is strictly increasing. Our main result is the following

Theorem. Using the notations mentioned above, the following equation holds

$$\overline{\mathcal{A}} = \sum_{i=1}^{n} \mathcal{K}_i \tag{3}$$

where  $\overline{\mathcal{A}}$  denotes the weak<sup>\*</sup> closure of  $\mathcal{A}$ ,

$$\mathcal{K}_{i} = \left\{ f \in L^{\infty}(D) : 0 \le f \le c_{i} - c_{i-1}, \int_{D} f \, \mathrm{d}x = (c_{i} - c_{i-1}) \sum_{k=i}^{n} \alpha_{k} \right\} \quad \text{for all } i = 2, \dots, n,$$

and  $\mathcal{K}_1 = \{c_1\}$ . Here,  $c_1$  denotes the constant function.

**Remark 1.** A direct consequence of the Theorem is the following useful observation. Suppose  $\beta_i \in \mathbb{R}$  satisfies  $0 < \beta_n < \beta_{n-1} < \cdots < \beta_1 < |D|$  and

$$\mathcal{K}_i = \left\{ f \in L^{\infty}(D) : 0 \le f \le 1, \int_D f \, \mathrm{d}x = \beta_i \right\} \quad \text{for all } i = 1, \dots, n$$

If we set  $\beta_0 = |D|$ ,  $\beta_{n+1} = 0$  and

$$\mathscr{A} = \left\{ \sum_{i=1}^{n+1} (i-1)\chi_{E_i} : E_i \subseteq D, \{E_i\} \text{ are mutually disjoint, } |E_i| = \beta_{i-1} - \beta_i \right\},\$$

then we have

$$\overline{\mathscr{A}} = \sum_{i=1}^{n} \mathscr{K}_i.$$

### 2. Proof of the Theorem

In the proof of the Theorem, we use the following important lemma from [2] which we include a sketch of its proof for the convenience of readers.

**Lemma.** Let 
$$f_1, f_2, ..., f_n \in L^{\infty}(D)$$
 such that  $\int_D f_i f_j \, dx = \int_0^{|D|} f_i^{\Delta} f_j^{\Delta} \, ds$  for all  $i, j = 1, 2, ..., n$ . Then,  

$$\sum_{i=1}^n \overline{\mathscr{R}(f_i)} = \overline{\mathscr{R}\left(\sum_{i=1}^n f_i\right)}.$$

*Here,*  $f_i^{\Delta}$  *denotes the decreasing rearrangement on* (0, |D|)*, i.e.*  $f_i^{\Delta}(s) := \max\{\alpha : \lambda_{f_i}(\alpha) \ge s\}$ .

Proof. We only sketch the proof here; the readers can refer to Theorem 3 in [2] for details.

The inclusion  $\overline{\mathscr{R}}(\sum_{i=1}^{n} f_i) \subseteq \sum_{i=1}^{n} \overline{\mathscr{R}}(f_i)$  follows from Theorem 18.10 in [5]. Now, we show the inclusion in the other direction. To this end, we set  $f = \sum_{i=1}^{n} f_i$  and utilize the condition that  $\int_D f_i f_j \, \mathrm{d}x = \int_0^{|D|} f_i^{\Delta} f_j^{\Delta} \, \mathrm{d}s$  to show the following

$$0 \leq \int_0^{|D|} \left( f^{\triangle} - \sum_{i=1}^n f_i^{\triangle} \right)^2 \mathrm{d}s \leq \int_D \left( f - \sum_{i=1}^n f_i \right)^2 \mathrm{d}x = 0.$$

This, in turn, implies

$$\left(\sum_{i=1}^{n} f_i\right)^{\Delta} = \sum_{i=1}^{n} f_i^{\Delta}.$$
(4)

Next, let  $h = \sum_{i=1}^{n} h_i \in \sum_{i=1}^{n} \overline{\mathscr{R}(f_i)}$  with  $h_i \in \overline{\mathscr{R}(f_i)}$  for i = 1, 2, ..., n. We can use the standard rearrangement techniques and (4) to derive

$$\int_0^{|D|} h^{\Delta} \,\mathrm{d}s = \int_0^{|D|} \left(\sum_{i=1}^n f_i\right)^{\Delta} \,\mathrm{d}s \quad \text{and} \quad \int_0^t h^{\Delta} \,\mathrm{d}s \le \int_0^t \left(\sum_{i=1}^n f_i\right)^{\Delta} \,\mathrm{d}s,$$

for all  $t \in (0, |D|)$ . This implies  $h \in \overline{\mathscr{R}(\sum_{i=1}^{n} f_i)}$ , by [1] or Proposition 5 in [2]. The proof of the Lemma is complete.

**Proof of the Theorem.** The proof of the Theorem is in fact an immediate consequence of the Lemma.

By setting  $c_0 = 0$ , the key to the proof will be the decomposition in (5). We define

$$f_i = (c_i - c_{i-1})\chi_{\bigcup_{k=i}^n E_k},$$

*i* = 1, 2, ..., *n*. We then set

$$f = \sum_{i=1}^{n} f_i.$$
(5)

Clearly,  $\mathcal{A} = \mathcal{R}(f)$ . On the other hand, for almost every  $s \in (0, |D|)$ , we have

$$f_i^{\Delta}(s) = (c_i - c_{i-1})\chi_{(0,\sum_{k=i}^n \alpha_k)}(s),$$

i = 1, 2, ..., n. For  $i, j \in \{1, 2, ..., n\}$  with  $i \le j$ , then we deduce, by direct computations, that

$$\int_{D} f_{i}(x) f_{j}(x) \, \mathrm{d}x = (c_{i} - c_{i-1})(c_{j} - c_{j-1}) \sum_{k=j}^{n} \alpha_{k} = \int_{0}^{|D|} f_{i}^{\Delta}(s) f_{j}^{\Delta}(s) \, \mathrm{d}s.$$
(6)

From (5), (6) and the Lemma, we infer that

$$\overline{\mathscr{A}} = \overline{\mathscr{R}(f)} = \overline{\mathscr{R}\left(\sum_{i=1}^{n} f_i\right)} = \sum_{i=1}^{n} \overline{\mathscr{R}(f_i)}.$$

Moreover, by Proposition 2.4 in [3], we have

$$\mathcal{K}_i := \overline{\mathcal{R}(f_i)} = \left\{ g \in L^{\infty}(D) : 0 \le g \le c_i - c_{i-1}, \int_D g \, \mathrm{d}x = (c_i - c_{i-1}) \sum_{k=i}^n \alpha_k \right\},\$$

i = 1, 2, ..., n. Notice that  $\mathscr{R}(f_1) = \{f_1\} = \{c_1\}$ , hence we infer  $\mathscr{K}_1 = \overline{\mathscr{R}(f_1)} = \{c_1\}$ . Therefore, the decomposition (3) follows.

**Remark 2.** It is important to mention that everything stated in this paper holds true if the Lebesgue measure is replaced by any other (finite) non-atomic measures.

This theorem has nice applications, for example, in spectral theory which we only outline here. Consider the eigenvalue problem

$$\begin{cases} -\Delta u = \lambda \rho(x) u, & \text{in } D\\ u = 0, & \text{on } \partial D, \end{cases}$$
(7)

where this boundary value problem models the displacement, denoted u, of a clamped membrane with density  $\rho(x)$  on the bounded domain D from the rest position. It is well known that if  $\rho$  is a non-trivial function in  $L^{\infty}_{+}(D)$ , then the eigenvalue problem (7) has a sequence of eigenvalues such that

$$0 < \lambda_1 < \lambda_2 \leq \ldots \rightarrow \infty$$
,

see for example [6].  $\lambda_1(\rho)$ , to emphasize its dependence on  $\rho$ , is called the principal eigenvalue and it can be formulated in terms of the Rayleigh quotient

$$\lambda_1(\rho) := \inf\left\{\frac{\int_D |\nabla \nu|^2 \,\mathrm{d}x}{\int_D \rho \,\nu^2 \,\mathrm{d}x} : \nu \in H^1_0(D), \int_D \rho \,\nu^2 \,\mathrm{d}x > 0\right\}.$$

One is interested in the following maximization and minimization problems

$$\sup_{\rho \in \mathcal{K}_1 + \mathcal{K}_2 + \dots + \mathcal{K}_n} \lambda_1(\rho) \quad \text{and} \quad \inf_{\rho \in \mathcal{K}_1 + \mathcal{K}_2 + \dots + \mathcal{K}_n} \lambda_1(\rho).$$
(8)

By using the Theorem, we can transform the above problems to the following rearrangement optimization problems

$$\sup_{\rho\in\overline{\mathcal{A}}}\lambda_{1}(\rho) \quad \text{and} \quad \inf_{\rho\in\overline{\mathcal{A}}}\lambda_{1}(\rho)$$

which can be solved by the results in [4, 8]. Moreover, one can prove that the optimization problems in (8) have optimal solutions which, in turn, give rise to free boundary problems related to the eigenvalue problem (7).

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