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# Simultaneous control for the heat equation with Dirichlet and Neumann boundary conditions

*Contrôle simultané de l'équation de la chaleur avec conditions aux limites de Dirichlet et Neumann*

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**Abstract.** It is well known that both the heat equation with Dirichlet or Neumann boundary conditions are null controllable as soon as the control acts in a non trivial domain (i.e. a set of positive measure). In this article, we show that for any couple of initial data  $(u_0, v_0)$  we can achieve the null control for both equations (Dirichlet and Neumann boundary conditions respectively) simultaneously with the same control function for both equations.

**Résumé.** Il est bien connu que l'équation de la chaleur avec aussi bien la condition au bord de Dirichlet que la condition de Neumann est contrôlable à 0 dès que le contrôle agit sur un domaine non trivial (i.e. de mesure positive). Dans cet article, nous montrons que pour tout couple de données initiales  $(u_0, v_0) \in L^2$ , le contrôle à 0 peut être réalisé simultanément avec la même fonction de contrôle pour les deux équations.

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## 1. Introduction and main results

Let us consider a smooth bounded domain  $\Omega \subset \mathbb{R}^d$  and let  $\omega \subset \Omega$  be a subset of positive measure  $|\omega| > 0$  and the following internal simultaneous controlability problem

$$\begin{cases} (\partial_t - \Delta)u = f \mathbf{1}_{(0,T) \times \omega}, & u|_{\partial\Omega} = 0, & u|_{t=0} = u_0, \\ (\partial_t - \Delta)v = f \mathbf{1}_{(0,T) \times \omega}, & \partial_\nu v|_{\partial\Omega} = 0, & v|_{t=0} = v_0. \end{cases} \quad (1)$$

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**Definition 1.** We shall say that the heat equation in  $\Omega$  is simultaneously null controlable with Dirichlet and Neumann boundary conditions if for any  $(u_0, v_0) \in L^2(\Omega)$  there exists  $f \in L^2((0, T) \times \omega)$  such that the solution of the system (1) satisfies

$$u|_{t>T} = 0, \quad v|_{t>T} = 0.$$

The question of simultaneous controllability of various partial differential equations has been raised in the literature (see for example [1, 3, 4, 6, 8] and the recent work [2] for more references on the subject), especially when the system involves some transmission mechanisms between the equations allowing to reduce the number of commands. The interest of our problem lies on the fact that both heat equations in (1) exhibit relatively independent dynamics and yet they can be steered to zero using *exactly the same control*. As no coupling exists between these two equations, this simultaneous controlability is at first glance counter intuitive. Yet, by considering the two new unknowns  $w_1 = u + v, w_2 = u - v$ , the simultaneous controlability reduces to the controlability of  $(w_1, w_2)$ , with a control acting only on the  $w_1$  component of the system. Notice that the system  $(w_1, w_2)$  is now coupled at the boundary by the transmission conditions

$$\partial_\nu w_1|_{\partial\Omega} = \partial_\nu w_2|_{\partial\Omega}, \quad w_1|_{\partial\Omega} = -w_2|_{\partial\Omega},$$

and we need to show that this coupling is sufficient. However, our strategy will follow a more direct path (the double manifold) and will not study *per se* this transmission problem.

### 1.1. Simultaneous controllability

Our first result is the following

**Theorem 2.** Let  $T > 0, \omega \subset \Omega$  of positive measure  $|\omega| > 0$ . Then the heat equation in  $\Omega$  is simultaneously null controlable with Dirichlet and Neumann boundary conditions.

**Remark 3.** It is classical that both the heat equation with Dirichlet or with Neumann conditions are null controlable. The novelty in Theorem 2 lies precisely on the fact that the null controlability can be achieved for any initial data  $(u_0, v_0) \in L^2(\Omega) \times L^2(\Omega)$  with the same control for both.

**Remark 4.** The proof we give below relies on the doubling manifold approach from [5]. This approach is very robust and allows rough domains (of class  $W^{2,\infty}$ , for instance) and rough space-dependent Laplace operators (Lipschitz coefficients).

$$\Delta = \frac{1}{\kappa(x)} \sum_{i,j} \partial_{x_i} g^{i,j}(x) \kappa(x) \partial_{x_j},$$

where we assume that the coefficients  $\kappa, g$  are Lipschitz and that  $g$  is uniformly elliptic. As will appear clearly, the proof (which is very simple once the results in [5] were established) shows that all the control results from [5] are true with the same control functions for the Dirichlet and Neumann heat equations.

**Remark 5.** It is an interesting question whether similar results might hold for the wave equation. We plan to address this question in a forthcoming paper. However, in this case, the analysis is much more involved and we do not expect to get such a general answer.

### 1.2. Simultaneous controllability and spectral inequalities

Let  $(e_\lambda^D)_\lambda$  be the spectral family associated to the Laplacian in  $\Omega$  with Dirichlet conditions, i.e.,

$$-\Delta e_\lambda^D = \lambda^2 e_\lambda^D, \quad e_\lambda^D|_{\partial\Omega} = 0 \tag{2}$$

and let  $(e_\mu^N)_\mu$  be the spectral family associated to the Laplacian in  $\Omega$  with Neumann conditions,

$$-\Delta e_\mu^N = \mu^2 e_\mu^N, \quad \partial_\nu e_\mu^N|_{\partial\Omega} = 0. \tag{3}$$

Let  $\omega \subset \Omega$  be a non-empty subset. In the spirit of [7], one can show that the spectral families  $(e_\lambda^D)_\lambda$  and  $(e_\mu^N)_\mu$  enjoy a concentration property on the subsets  $\omega$  as long as they are not too small. In [5] the authors shows the following: given  $\omega$  with  $|\omega| > 0$ , there exist constants  $C, D$  such that all the spectral truncations

$$\Pi_\Lambda^D u := \sum_{\lambda \leq \Lambda} u_\lambda e_\lambda^D, \quad u \in L^2(\Omega), \quad \Lambda > 0,$$

satisfy the estimate (cf. [5, Theorem 1]):

$$\|\Pi_\Lambda^D u\|_{L^\infty(\Omega)} \leq C e^{C\Lambda} \|\mathbb{1}_\omega \Pi_\Lambda^D u\|_{L^1(\Omega)}, \quad \forall u \in L^2(\Omega). \tag{4}$$

The analogous estimate also holds for the spectral truncations of  $(e_\mu^N)_\mu$ , defined by

$$\Pi_\Lambda^N u := \sum_{\mu \leq \Lambda} u_\mu e_\mu^N, \quad u \in L^2(\Omega), \quad \Lambda > 0.$$

In this note we show that these spectral inequalities also hold *simultaneously* (i.e. we can estimate each spectral projector by the sum on arbitrary small set of positive measures).

**Theorem 6.** *Let  $\omega \subset \Omega$  with  $|\omega| > 0$ . There exist  $C, D > 0$  such that for any  $\Lambda > 0$ , we have*

$$\|\Pi_\Lambda^D u\|_{L^\infty(\Omega)} + \|\Pi_\Lambda^N v\|_{L^\infty(\Omega)} \leq C e^{C\Lambda} \|\mathbb{1}_\omega (\Pi_\Lambda^D u + \Pi_\Lambda^N v)\|_{L^1(\omega)}, \quad \forall u, v \in L^2(\Omega). \tag{5}$$

## 2. Double manifold and spectral estimates

In this section we recall a result from [5], which allows to glue any given manifold  $M$  with a copy of itself along its boundary, in order to produce a *double manifold* without boundary. This will be a crucial point in the analysis below.

### 2.1. The double manifold

Let  $(M, g)$  be a compact Riemannian manifold of class  $C^1 \cap W^{1,\infty}$ .

Let  $\Delta$  be the Laplace–Beltrami operator on  $M$  and let  $(e_k)$  be a family of eigenfunctions of  $-\Delta$ , with eigenvalues  $\lambda_k^2 \rightarrow +\infty$  forming a Hilbert basis of  $L^2(M)$ .

$$-\Delta e_k^{D;N} = \lambda_k^2 e_k, \quad e_k^D|_{\partial M} = 0 \text{ (Dirichlet condition) or } \partial_\nu e_k^N|_{\partial M} = 0 \text{ (Neumann condition).}$$

Let be  $\widetilde{M}$  the double space made of two copies of  $\overline{M}$

$$\widetilde{M} = \overline{M} \times \{-1, 1\} / \partial M,$$

where we identified the points on the boundary,  $(x, -1)$  and  $(x, 1)$ ,  $x \in \partial M$ . In the double manifold  $\widetilde{M}$  we have the following result.

**Theorem 7 (The double manifold, [5, Theorem 7]).** *Let  $g$  be given. There exists a  $W^{2,\infty}$  structure on the double manifold  $\widetilde{M}$ , a metric  $\widetilde{g}$  of class  $W^{1,\infty}$  on  $\widetilde{M}$ , and a density  $\widetilde{\kappa}$  of class  $W^{1,\infty}$  on  $\widetilde{M}$  such that the following holds.*

- The maps

$$i^\pm : x \in M \rightarrow (x, \pm 1) \in \widetilde{M} = M \times \{1, -1\} / \partial M$$

are isometric embeddings.

- The density induced on each copy of  $M$  is the density  $\kappa$ ,

$$\widetilde{\kappa}|_{M \times \{1, -1\}} = \kappa.$$

- For any eigenfunction  $e$  with eigenvalue  $\lambda^2$  of the Laplace operator  $-\Delta = -\frac{1}{\kappa} \operatorname{div} g^{-1} \kappa \nabla$  with Dirichlet boundary conditions on  $M$ , there exists an eigenfunction  $\tilde{e}$  with the same eigenvalue  $\lambda^2$  of the Laplace operator  $-\Delta = -\frac{1}{\tilde{\kappa}} \operatorname{div} \tilde{g}^{-1} \tilde{\kappa} \nabla$  on  $\tilde{M}$  such that

$$\tilde{e}(x, 1) = e(x), \quad \tilde{e}(x, -1) = -e(x) \tag{6}$$

*i.e. gluing  $e$  and  $-e$  along the boundary (notice that it makes sense since  $e|_{\partial M} = 0$ ) gives an eigenfunction of the Laplace operator on the double manifold*

- For any eigenfunction  $e$  with eigenvalue  $\lambda^2$  of the Laplace operator  $-\Delta = -\frac{1}{\kappa} \operatorname{div} g^{-1} \kappa \nabla$  with Neumann boundary conditions on  $M$ , there exists an eigenfunction  $\tilde{e}$  with the same eigenvalue  $\lambda^2$  of the Laplace operator  $-\Delta = -\frac{1}{\tilde{\kappa}} \operatorname{div} \tilde{g}^{-1} \tilde{\kappa} \nabla$  on  $\tilde{M}$  such that

$$\forall x \in M, \tilde{e}(x, 1) = e(x), \quad \tilde{e}(x, -1) = e(x) \tag{7}$$

*i.e. gluing two copies of  $e$  along the boundary gives an eigenfunction of the Laplace operator on the double manifold*

- Conversely, there exists a Hilbert basis of  $L^2(\tilde{M})$  composed of eigenfunctions of the Laplace operator  $\tilde{\Delta}$  which are either such extensions of Dirichlet Laplace eigenfunctions in  $M$  or such extensions of Neumann Laplace eigenfunctions in  $M$ .

**Remark 8.** The last property was not stated explicitly in [5, Theorem 7], but it is straightforward as the vector space generated by such eigenfunctions is clearly dense in  $L^2(\tilde{M})$ .

### 2.2. Spectral projector on the double manifold and proof of Theorem 6

Let us denote by  $\tilde{\Pi}_\Lambda$  the spectral projector on the manifold  $\tilde{M}$ . Let  $u, v \in L^2(M)$  and define the function

$$\tilde{u}(x, 1) = (u + v)(x), \quad \tilde{u}(x, -1) = (-u + v)(x). \tag{8}$$

Clearly if

$$u = \sum_k u_k e_k^D, \quad v = \sum_k v_k e_k^N,$$

we get

$$\tilde{u} = \sum_k u_k \tilde{e}_k^D + v_k \tilde{e}_k^N.$$

According to the reflection principle of the previous section, we can link the Dirichlet and Neumann spectral projectors on  $M$  and the spectral projector on  $\tilde{M}$  by the relation

$$\tilde{\Pi}_\Lambda(\tilde{u})(\cdot, 1) = \Pi_\Lambda^D(u(\cdot)) + \Pi_\Lambda^N(v(\cdot)), \quad \tilde{\Pi}_\Lambda(\tilde{u})(\cdot, -1) = -\Pi_\Lambda^D(u(\cdot)) + \Pi_\Lambda^N(v(\cdot)). \tag{9}$$

**Theorem 9 ([5, Theorem 1]).** *Let  $\tilde{\omega} \subset \tilde{M}$  with positive Lebesgue measure. Then, there exists  $C > 0$  such that for any  $\Lambda > 0$  and any  $\tilde{u} \in L^2(\tilde{M})$ , we have*

$$\|\tilde{\Pi}_\Lambda \tilde{u}\|_{L^\infty(\tilde{M})} \leq C e^{C\Lambda} \|1_{\tilde{\omega}} \tilde{\Pi}_\Lambda \tilde{u}\|_{L^1(\tilde{\omega})}. \tag{10}$$

We can now prove Theorem 6. Indeed, let  $\omega \subset M$  of positive Lebesgue measure. Let  $\tilde{\omega} = \omega \times \{1\}$ . According to Theorem 9 and (9), we get for any  $u, v \in L^2(M)$ ,

$$\begin{aligned} \|\Pi_\Lambda^D u\|_{L^\infty(M)}^2 + \|\Pi_\Lambda^N v\|_{L^\infty(M)}^2 &\leq \|\Pi_\Lambda^D u + \Pi_\Lambda^N v\|_{L^\infty(M)}^2 + \|\Pi_\Lambda^D u - \Pi_\Lambda^N v\|_{L^\infty(M)}^2 \\ &= \|\tilde{\Pi}_\Lambda \tilde{u}\|_{L^\infty(\tilde{M})}^2 \leq C e^{C\Lambda} \|1_{\tilde{\omega}} \tilde{\Pi}_\Lambda \tilde{u}\|_{L^1(\tilde{\omega})}^2 \\ &= C e^{C\Lambda} \|1_{\omega \times \{1\}} \tilde{\Pi}_\Lambda \tilde{u}\|_{L^1(\tilde{\omega})}^2 = C e^{C\Lambda} \|1_\omega \Pi_\Lambda^D u + \Pi_\Lambda^N v\|_{L^1(\omega)}^2. \end{aligned} \tag{11}$$

### 2.3. Control and the double manifold

To prove our control result, we could just apply the spectral projector estimate we just proved and some functional analysis. Here we preferred to prove the result directly on the double manifold. We start with

**Theorem 10 ([5, Theorem 2]).** *Let  $\tilde{\omega} \subset \tilde{M}$  be a measurable set with  $|\tilde{\omega}| > 0$ . Then, for every  $T > 0$  and every  $\tilde{u}_0 \in L^2(M)$ , there exists  $\tilde{f} \in L^2((0, T) \times \tilde{\omega})$  such that the solution to the heat equation on  $\tilde{M}$  satisfies*

$$\tilde{u}|_{t \geq T} = 0.$$

We can now prove Theorem 2. For any  $u, v \in L^2(M)$ , let us define  $\tilde{u}$  by (8), and for any  $\omega \subset M$  of positive measure, let  $\tilde{\omega} = \omega \times \{1\}$ . According to Theorem 10, for every  $T > 0$ , there exists  $\tilde{f} \in L^2((0, T) \times \tilde{\omega})$  such that

$$(\partial_t - \tilde{\Delta})\tilde{U} = \tilde{f}\mathbb{1}_{(0,T) \times \tilde{\omega}}, \quad \tilde{U}|_{t=0} = \tilde{u}, \quad \tilde{U}|_{t \geq T} = 0. \tag{12}$$

Let us define next

$$u(t, x) = \tilde{U}(t, x, 1) - \tilde{U}(t, x, -1), \quad v(t, x) = \tilde{U}(t, x, 1) + \tilde{U}(t, x, -1),$$

where  $\tilde{U}$  is defined by (12). Notice that  $u$  clearly satisfies the Dirichlet boundary condition while  $v$  satisfies the Neumann boundary condition. This second condition is not obvious but comes from the construction of the double manifold in [5]. Indeed, in our construction, we defined normal coordinate system near any point in the boundary of  $M$  such that  $M = \{x_n > 0\}$ , and then we glued the two copies defined by  $M \times \{1\} = \{x_n > 0\}$ ,  $M \times \{-1\} = \{x_n < 0\}$  by the relation

$$(x, 1) = (x_n, x', 1), (x, -1) = (-x_n, x', -1),$$

which implies

$$\partial_\nu v = \partial_{x_n}(\tilde{U}(t, x, 1) + \tilde{U}(t, x, -1))|_{x_n=0} = \partial_{x_n}(\tilde{U})(t, x, 1) - \partial_{x_n}(\tilde{U})(t, x, -1) = 0.$$

Now, by definition of  $u$  and  $v$  we have

$$(\partial_t - \Delta)u = \tilde{f}(t, x, 1)\mathbb{1}_{(0,T) \times \omega} - \tilde{f}(t, x, -1)\mathbb{1}_{(0,T) \times \tilde{\omega}} = f(t, x)\mathbb{1}_{(0,T) \times \omega},$$

as  $\tilde{f}(t, x, -1)\mathbb{1}_{(0,T) \times \tilde{\omega}} = 0$  by the choice of  $\tilde{\omega} = \omega \times \{1\}$ . By the same token, we have

$$(\partial_t - \Delta)v = \tilde{f}(t, x, 1)\mathbb{1}_{(0,T) \times \omega} + \tilde{f}(t, x, -1)\mathbb{1}_{(0,T) \times \tilde{\omega}} = f(t, x)\mathbb{1}_{(0,T) \times \omega}.$$

As a consequence,  $u$  and  $v$  solve (1) with control  $f\mathbb{1}_{(0,T) \times \omega}$ . Finally, using (12), we get

$$u|_{t \geq T} = 0, \quad v|_{t \geq T} = 0,$$

which ends the proof.

### Declaration of interests

The authors do not work for, advise, own shares in, or receive funds from any organization that could benefit from this article, and have declared no affiliations other than their research organizations.

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