



ACADÉMIE  
DES SCIENCES  
INSTITUT DE FRANCE

# *Comptes Rendus*

---

# *Mathématique*


Manuel Krannich and Alexander Kupers

**A note on homotopy and pseudoisotopy of diffeomorphisms of 4-manifolds**

Volume 362 (2024), p. 1515-1520

Online since: 14 November 2024

<https://doi.org/10.5802/crmath.663>

 This article is licensed under the  
CREATIVE COMMONS ATTRIBUTION 4.0 INTERNATIONAL LICENSE.  
<http://creativecommons.org/licenses/by/4.0/>



*The Comptes Rendus. Mathématique are a member of the  
Mersenne Center for open scientific publishing*  
[www.centre-mersenne.org](http://www.centre-mersenne.org) — e-ISSN : 1778-3569



Research article / *Article de recherche*  
Geometry and Topology / *Géométrie et Topologie*

# A note on homotopy and pseudoisotopy of diffeomorphisms of 4-manifolds

*Une note sur l'homotopie et la pseudoisotopie des diffeomorphismes des 4-variétés*

Manuel Krannich <sup>\*,a</sup> and Alexander Kupers <sup>b</sup>

<sup>a</sup> Department of Mathematics, Karlsruhe Institute of Technology, 76131 Karlsruhe, Germany

<sup>b</sup> Department of Computer and Mathematical Sciences, University of Toronto Scarborough,  
1265 Military Trail, Toronto, ON M1C 1A4, Canada

E-mails: [krannich@kit.edu](mailto:krannich@kit.edu), [a.kupers@utoronto.ca](mailto:a.kupers@utoronto.ca)

**Abstract.** This note serves to record examples of diffeomorphisms of closed smooth 4-manifolds  $X$  that are homotopic but not pseudoisotopic to the identity, and to explain why there are no such examples when  $X$  is orientable and its fundamental group is a free group.

**Résumé.** Cette note a pour but de présenter des exemples de diffeomorphismes d'une 4-variété lisse  $X$  qui sont homotopes mais pas pseudo-isotopes à l'identité, et d'expliquer pourquoi de tels exemples n'existent pas quand  $X$  est orientable de groupe fondamental libre.

**Keywords.** 4-Manifolds, diffeomorphisms, pseudoisotopy, homotopy, surgery theory.

**Mots-clés.** variété de dimension 4, difféomorphisme, homotopie, chirurgie.

**2020 Mathematics Subject Classification.** 57R52, 57R67, 57K40.

**Funding.** AK acknowledges the support of the Natural Sciences and Engineering Research Council of Canada (NSERC) [funding reference number 512156 and 512250]. AK was supported by an Alfred P. Sloan Research Fellowship.

*Manuscript received 23 February 2024, revised 19 June 2024, accepted 7 July 2024.*

Recall that two diffeomorphisms  $\varphi_0$  and  $\varphi_1$  of a smooth manifold  $X$  are called *pseudoisotopic* if there exists a diffeomorphism of  $X \times [0, 1]$  that restricts to  $\varphi_i$  on  $X \times \{i\}$  for  $i = 0, 1$ .

As part of the K3 project<sup>1</sup>, we were asked the following question:

**Question.** *Is any diffeomorphism of a connected closed smooth 4-manifold  $X$  that is homotopic to the identity also pseudoisotopic to the identity?*

Equivalently, the question is whether homotopy implies pseudoisotopy for diffeomorphisms of connected closed smooth 4-manifolds  $X$ . If the fundamental group  $\pi_1(X)$  vanishes or if  $X$  is orientable and  $\pi_1(X) \cong \mathbf{Z}$ , the answer to this question and its analogue in the topological category is known to be positive (see [10, Theorem 1], [13, Proposition 2.2], and [16, p. 51]).

\* Corresponding author

<sup>1</sup> See <https://aimath.org/workshops/upcoming/kirbylist/>.

The purpose of this note is twofold: firstly, we illustrate how classical surgery theory allows one to answer the general form of the question in the negative.

**Theorem A.** *There exists a diffeomorphism of a smooth closed 4-manifold  $X$  that is homotopic but neither smoothly nor topologically pseudoisotopic to the identity.*

More concretely, we explain why a diffeomorphism as in Theorem A exists for any 4-manifold of the form  $X = Y \sharp^g (S^2 \times S^2)$  for large enough  $g \geq 0$  depending on  $Y$ , where  $Y$  is any connected compact smooth stably parallelisable 4-manifold whose fundamental group  $\pi := \pi_1(Y)$  satisfies:

- (1)  $H_1(\pi)/(2\text{-torsion})$  is not annihilated by multiplication by 3 and
- (2) the 5th simple  $L$ -group  $L_5^s(\mathbf{Z}[\pi])$  of  $\mathbf{Z}[\pi]$  with the standard involution vanishes.

There are many 4-manifolds with these properties: any finitely presented group  $\pi$  arises as  $\pi_1(Y)$  of a connected closed smooth stably parallelisable 4-manifold  $Y$  [7, Proof of Theorem 1] and there are many choices for  $\pi$  that satisfy (2), such as finite groups  $\pi$  of odd order [1] or more generally products  $\pi = \pi_{\text{odd}} \times \mathbf{Z}/2^k$  where  $\pi_{\text{odd}}$  has odd order [5, p. 227, 12.1, 12.2], e.g.  $\pi$  can be any finite cyclic group. If  $\pi_{\text{odd}}$  has a nontrivial element of order  $\neq 3$ , then  $\pi$  also satisfies (1).

**Example.** The simplest example for  $Y$  that satisfies the conditions is the result of a surgery along an embedding  $e: S^1 \times D^3 \hookrightarrow S^1 \times S^3$  such that (a) the class  $[e] \in \pi_1(S^1 \times S^3) \cong \mathbf{Z}$  is  $\pm 5$  and (b) the result of the surgery is stably parallelisable (which is always possible; see [11, Theorem 2]).

The second purpose of this note is to observe that a combination of the surgery exact sequence with arguments in work of Shaneson allows one to widen the class of examples for which the answer to the Question is positive from orientable 4-manifolds  $X$  such that  $\pi_1(X)$  is trivial or free of rank 1 to those for which  $\pi_1(X)$  is a free group  $F_n$  of arbitrary finite rank  $n \geq 0$ .

**Theorem B.** *For diffeomorphisms of connected closed smooth orientable 4-manifolds with free fundamental group, homotopy implies pseudoisotopy.*

**Remark.** Combined with recent work of Gabai [4, Theorem 2.5, Remark 2.10], this implies that diffeomorphisms of 4-manifolds  $X$  as in Theorem B that are homotopic are also stably isotopic, i.e. are isotopic when extended by the identity to diffeomorphisms of  $X \sharp^g (S^2 \times S^2)$  for some  $g \geq 0$  after isotoping them to fix an embedded disc to form the connected sum.

**Proof of Theorem A**

The proof centres around the diagram of groups

$$\begin{array}{ccccc}
 \pi_0 \text{hAut}_\partial^s(X \times I) & \xrightarrow{\textcircled{1}} & S_\partial^{s, \text{triv}}(X \times I) & \xrightarrow{\textcircled{2}} & \pi_0 \widetilde{\text{Diff}}_\partial(X) & \xrightarrow{\textcircled{3}} & \pi_0 \text{hAut}_\partial^s(X) \\
 & & \cap & & & & \\
 & & S_\partial^s(X \times I) & & & & \\
 & & \downarrow \textcircled{4} & & & & \\
 & & [\Sigma(X/\partial X), G/O]_* & \xrightarrow{\textcircled{6}} & [\Sigma(X/\partial X), \text{BO}]_* & & \\
 & & \downarrow \textcircled{5} & & & & \\
 & & L_5^s(\mathbf{Z}[\pi_1(X)], w_1) & & & & 
 \end{array} \tag{1}$$

for any compact connected smooth 4-manifold  $X$ . The terms and maps involved are:

- (I)  $\pi_0 \widetilde{\text{Diff}}_\partial(X)$  and  $\pi_0 \text{hAut}_\partial^s(X)$  are the groups of diffeomorphisms (or simple homotopy equivalences) of  $X$  that fix  $\partial X$  pointwise, up to smooth pseudoisotopy (or homotopy) fixing  $\partial X$ ,

- (II)  $S_\partial^s(X \times I)$  is the *simple structure set* of the pair  $(X \times I, \partial(X \times I))$  in the sense of surgery theory [17, Chapter 10], consisting of equivalence classes of pairs  $(W, \varphi)$  of a compact 5-manifold  $W$  and a simple homotopy equivalence  $\varphi: W \rightarrow X \times I$  that restricts to a diffeomorphism  $\varphi|_{\partial W}: \partial W \rightarrow \partial(X \times I)$ . The group structure is by “stacking”. Note that the manifold  $W$  becomes via  $\varphi|_{\partial W}$  a relative self  $s$ -cobordism of  $(X, \partial X)$  with an identification of the boundary bordism with  $\partial X \times I$ , but since  $W$  is 5-dimensional this  $s$ -cobordism need not be trivial. Restricting to those classes of pairs  $(W, \varphi)$  for which  $W$  is trivial (i.e. diffeomorphic to  $X \times I$  relative to  $\partial X \times I$ , but not necessarily relative to  $X \times \{0, 1\}$ ) defines a subgroup  $S_\partial^{s, \text{triv}}(X \times I) \subseteq S_\partial^s(X \times I)$ .
- (III)  $[\Sigma(X/\partial X), \text{BO}]_*$  and  $[\Sigma(X/\partial X), \text{G/O}]_*$  consist of pointed homotopy classes of maps from the reduced suspension of  $X/\partial X$  to the classifying spaces  $\text{BO}$  and  $\text{G/O}$  for stable vector bundles and for stable vector bundles with a trivialisation of the underlying stable spherical fibration,
- (IV)  $L_5^s(\mathbf{Z}[\pi_1(X)], w_1)$  is the 5th simple  $L$ -group of the group ring  $\mathbf{Z}[\pi_1(X)]$  with the involution determined by orientation character  $w_1$ , in the sense of surgery theory (see loc.cit.).
- (V) The map ① sends  $[\varphi]$  to  $[X \times I, \varphi]$ , ② sends  $[X \times I, \varphi]$  to  $[\varphi|_{X \times \{1\}} \circ \varphi|_{X \times \{0\}}^{-1}]$ , ③ sends  $[\varphi]$  to  $[\varphi]$ , ④ and ⑤ take normal invariants and surgery obstructions respectively (see loc.cit.), and ⑥ is induced by forgetting the trivialisation of the spherical fibration.

We will use the following facts about this diagram:

- (a) The top row and middle column are exact; the former by inspection and the latter by surgery theory (see e.g. Chapter 10 loc.cit.).
- (b) We have  $[\Sigma(X/\partial X), \text{G/O}]_* \cong \text{H}^1(X, \partial X; \mathbf{Z}/2) \oplus \text{H}^3(X, \partial X; \mathbf{Z})$  (see e.g. [9, p. 398]).
- (c) The composition  $S_\partial^s(X \times I) \rightarrow [\Sigma(X/\partial X), \text{BO}]_*$  has the following description (cf. [17, p. 113–114]): for  $[W, \varphi] \in S_\partial^s(X \times I)$ , choose a homotopy inverse  $\tilde{\varphi}$  of  $\varphi$  with  $\tilde{\varphi}|_{\partial(X \times I)} = \varphi|_{\partial W}^{-1}$ , consider the stable vector bundle  $\tilde{\varphi}^*(\nu_W) \oplus \tau_{X \times I}$  over  $X \times I$  where  $\nu_{(-)}$  and  $\tau_{(-)}$  is the stable normal and tangent bundle. Together with the trivialisation of  $(\tilde{\varphi}^*(\nu_W) \oplus \tau_{X \times I})|_{\partial(X \times I)}$  induced by the derivative of  $\tilde{\varphi}|_{\partial(X \times I)}$ , this defines a class in  $[(X \times I)/\partial(X \times I), \text{BO}]_* = [\Sigma(X/\partial X), \text{BO}]_*$ .
- (d) If  $X$  arises as a codimension 0 submanifold  $X \subset \text{int}(\bar{X})$  of the interior of a compact connected smooth 4-manifold  $\bar{X}$ , there is a morphism  $S_\partial^s(X \times I) \rightarrow S_\partial^s(\bar{X} \times I)$  given by sending  $(W, \varphi)$  to  $W \cup_{\partial X \times I} (\bar{X} \setminus \text{int}(X) \times I)$  and  $\varphi$  to  $(\varphi \cup_{\partial X \times I} \text{id})$ . This preserves the triv-subgroups from (II). Moreover, from (c) one sees that this morphism is compatible with the map  $[\Sigma(X/\partial X), \text{BO}]_* \rightarrow [\Sigma(\bar{X}/\partial \bar{X}), \text{BO}]_*$  given by precomposition with the map  $\Sigma(\bar{X}/\partial \bar{X}) \rightarrow \Sigma(X/\partial X)$  induced by collapsing  $\bar{X} \setminus \text{int}(X)$ . In particular, if  $\partial X \neq \emptyset$ , there is a stabilisation morphism  $S_\partial^s(X \times I) \rightarrow S_\partial^s(X \# (S^2 \times S^2) \times I)$  by viewing  $X$  as a submanifold of  $X \cup_{\partial X} ((\partial X \times I) \# S^2 \times S^2) \cong X \# (S^2 \times S^2)$ .
- (e) If  $\partial X \neq \emptyset$ , then by the stable  $s$ -cobordism theorem [12, Theorem 1.1], for any element  $x \in S_\partial^s(X \times I)$  there is a number  $g \geq 0$  depending on  $x$  such that the image of  $x$  under the iterated stabilisation map  $S_\partial^s(X \times I) \rightarrow S_\partial^s(X \# (S^2 \times S^2)^{\#g} \times I)$  from (d) lies in the triv-subgroup from (II).
- (f) After localisation  $(-)[\frac{1}{2}]$  away from 2 and Postnikov 7-truncation  $\tau_{\leq 7}(-)$  the spaces  $\text{G/O}$  and  $\text{BO}$  are both equivalent to  $K(\mathbf{Z}[\frac{1}{2}], 4)$  and the map  $\tau_{\leq 7}(\text{G/O})[\frac{1}{2}] \rightarrow \tau_{\leq 7}(\text{BO})[\frac{1}{2}]$  is induced by multiplication by  $\pm 3$ . This follows from the computation of the stable homotopy groups of spheres in small degrees and the surjectivity of the stable  $J$ -homomorphism in degree 3.

If  $X$  is stably parallelisable and  $\pi_1(X)$  satisfies the conditions (1) and (2) (let us call such manifolds *admissible* for brevity), we can add to this list:

- (g) The map ④ is surjective as  $L_5^s(\mathbf{Z}[\pi_1(X)], w_1) = 0$  by (2) since  $X$  is orientable.
- (h) The composition  $(\textcircled{6} \circ \textcircled{4} \circ \textcircled{1}): \pi_0 \text{hAut}_\partial^s(X \times I) \rightarrow [\Sigma(X/\partial X), \text{BO}]_*$  is trivial. This follows from the descriptions of ① and ⑥  $\circ$  ④ in (V) and (c) using that  $X$  is stably parallelisable.

(i) By (b) and Poincaré duality we have  $[\Sigma(X/\partial X), G/O]_* \cong H_1(X; \mathbf{Z}) \oplus H^1(X, \partial X; \mathbf{Z}/2)$ . As a result of (1) there exists an element  $x \in H_1(X; \mathbf{Z})$  with  $3 \cdot x \neq 0 \in H_1(X; \mathbf{Z}[\frac{1}{2}])$ . By (g) the class  $x$  lifts along ④ to  $S^s_\partial(X \times I)$  and since  $[\Sigma(X/\partial X), G/O[\frac{1}{2}]]_* \rightarrow [\Sigma(X/\partial X), \text{BO}[\frac{1}{2}]]_*$  is given by multiplication by 3 in view of (f), it follows that  $x$  maps nontrivially to  $[\Sigma(X/\partial X), \text{BO}[\frac{1}{2}]]_*$ . In particular the composition  $S^s_\partial(X \times I) \rightarrow [\Sigma(X/\partial X), \text{BO}[\frac{1}{2}]]_* \cong H_1(X; \mathbf{Z}[\frac{1}{2}])$  is nontrivial.

Combining all this, the proof goes as follows: given an admissible 4-manifold  $Y$ , the claim is that there is a  $g \geq 0$  and a class in the kernel of ③ for  $X = Y \#^g(S^2 \times S^2)$  that maps nontrivially to the group  $\pi_0 \overline{\text{Homeo}}(X)$  of topological pseudoisotopy classes of homeomorphisms. We fix an embedded disc  $D^4 \subset \text{int}(Y)$  and set  $Y^\circ := Y \setminus \text{int}(D^4)$  which is again admissible. By (i) there is a class  $x \in S^s_\partial(Y^\circ \times I)$  that maps nontrivially to  $[\Sigma(Y^\circ/\partial Y^\circ), \text{BO}[\frac{1}{2}]]_*$ . Using (e), since  $\partial Y^\circ \neq \emptyset$  we find  $g \geq 0$  such that the image  $x_g$  of  $x$  under  $g$ -fold stabilisation lies in  $S^{s, \text{triv}}_\partial(Y^\circ \#^g(S^2 \times S^2) \times I)$ . Using the inclusion  $Y^\circ \#^g(S^2 \times S^2) \subset Y \#^g(S^2 \times S^2)$  we obtain via (d) an element  $\overline{x}_g$  in  $S^{s, \text{triv}}_\partial(Y \#^g(S^2 \times S^2) \times I)$ . By the compatibility part of (d) the image of this element in  $[\Sigma(Y \#^g(S^2 \times S^2)/\partial(Y \#^g(S^2 \times S^2))), \text{BO}[\frac{1}{2}]]_*$  is the image of  $x$  under the composition  $S^s_\partial(Y^\circ \times I) \rightarrow [\Sigma(Y^\circ/\partial Y^\circ), \text{BO}[\frac{1}{2}]]_* \rightarrow [\Sigma(Y \#^g(S^2 \times S^2)/\partial(Y \#^g(S^2 \times S^2))), \text{BO}[\frac{1}{2}]]_*$ , so it is nontrivial since it is not in the kernel of the first map by choice of  $x$  and because the second map is in light of (f), (d) and Poincaré duality an isomorphism since the inclusion  $Y^\circ \subset Y \#^g(S^2 \times S^2)$  is an isomorphism on first homology. Using (h) this implies that  $\overline{x}_g$  is not in the image of ① for  $X := Y \#^g(S^2 \times S^2)$ , so its image under ② is a nontrivial element in the kernel of ③. To see that this element is also nontrivial in  $\pi_0 \overline{\text{Homeo}}(X)$ , one argues as follows: by forgetting smoothness the diagram (1) maps compatibly to the corresponding diagram in the topological category, so it suffices to show that  $\overline{x}_g$  is, when mapped to the topological version of  $S^s_\partial(X \times I)$ , still not hit by the topological analogue of ①. By the way we detected this element, it suffices to show that the map  $[\Sigma(X/\partial X), \text{BO}[\frac{1}{2}]]_* \rightarrow [\Sigma(X/\partial X), \text{BTop}[\frac{1}{2}]]_*$  induced by the map  $\text{BO} \rightarrow \text{BTop}$  classifying the underlying stable Euclidean space bundle of a stable vector bundle is injective. This holds because  $\tau_{\leq 7}(\text{BO})[\frac{1}{2}] \rightarrow \tau_{\leq 7}(\text{BTop})[\frac{1}{2}]$  is an equivalence (see e.g. [8, p. 246, 5.0, (5)]).

**Remark.** In dimensions  $d \geq 5$ , it is significantly easier to produce examples as in Theorem A, even 1-connected ones, for example  $X = S^3 \times S^n$  for any  $n \geq 2$  works. This can be shown by a variant of the strategy above, but for  $n \geq 3$  there is also a more elementary argument: choose  $[\varphi] \in \pi_3(\text{SO}(n+1))$  that maps to a nontorsion class in  $\pi_3(\text{SO}) \cong \mathbf{Z}$  and lies in the kernel of the map induced by the forgetful map  $\text{SO}(n+1) \rightarrow \text{hAut}(S^n)$  (this is possible if and only if  $n \geq 3$ ) and consider the orientation-preserving diffeomorphism  $t_\varphi$  of  $S^3 \times S^n$  given by  $t_\varphi(x, v) = (x, \varphi(x) \cdot v)$ . Since the image of  $\varphi$  in  $\pi_3(\text{hAut}(S^n))$  is trivial,  $t_\varphi$  is homotopic to the identity. With respect to the standard stable framing of  $S^3 \times S^n$ , the stable derivative of  $t_\varphi$  in  $[S^3 \times S^n, \text{SO}] \cong \pi_3(\text{SO}) \oplus \pi_n(\text{SO}) \oplus \pi_{n+3}(\text{SO})$  is given by the stabilisation of  $[\varphi]$  in the first term, so it is nontrivial by choice of  $\varphi$ . This implies that  $t_\varphi$  is not pseudoisotopic to the identity, and since the image of  $\varphi$  in  $\pi_3(\text{STop})$  is nontrivial as  $\mathbf{Z} \cong \pi_3(\text{SO}) \rightarrow \pi_3(\text{STop}) \cong \mathbf{Z} \oplus \mathbf{Z}/2$  is injective,  $t_\varphi$  is also not topologically pseudoisotopic to the identity.

**Proof of Theorem B**

For a connected closed smooth orientable 4-manifold  $X$  with  $\pi_1(X) \cong F_n$  for some  $n \geq 0$ , the claim is that the map ③ in (1) is injective which is by exactness of the top row equivalent to showing that ① is surjective. To see this, we use that, since they are part of the surgery exact sequence (see e.g. [17, Chapter 10]), the maps ④ and ⑤ can be extended to the left to an exact sequence of groups (note that since  $X$  is orientable and closed, the involution on  $\mathbf{Z}[\pi_1(X)]$  is the standard one and we have  $X/\partial X = X_+ := X \sqcup \{*\}$ )

$$L^s_6(\mathbf{Z}[\pi_1(X)]) \xrightarrow{\textcircled{7}} S^s_\partial(X \times I) \xrightarrow{\textcircled{4}} [\Sigma(X_+), G/O]_* \xrightarrow{\textcircled{5}} L^s_5(\mathbf{Z}[\pi_1(X)]). \tag{2}$$

The map ⑦ turns out to be trivial: choosing an embedded disc  $D^4 \subset X$  and using the naturality of the surgery exact sequence in codimension 0 embeddings, this follows by combining that  $L_6^s(\mathbf{Z}[1]) \rightarrow L_6^s(\mathbf{Z}[F_n])$  is an isomorphism [2, Corollary 6] and that  $S_\partial^s(D^4 \times I) = 0$  as a consequence of the solution of the 5-dimensional smooth Poincaré conjecture. Since ⑦ is trivial, the map ④ is injective. In the case  $n = 0$ , so if  $\pi_1(X)$  and thus  $H_1(X)$  vanish,  $[\Sigma(X_+), G/O]_*$  vanishes by (b) and Poincaré duality, so it follows from exactness of (2) that  $S_\partial^s(X \times I)$  vanishes, so in particular ① is surjective and the proof is finished in this case.

For  $n > 0$ , the proof that ① is surjective is more subtle and follows by adapting arguments of Shaneson in the case  $n = 1$ : as a first step, one argues as in [15, p. 349] that the composition ⑥ ◦ ④ is trivial: By “gluing the ends of  $X \times I$ ” the composition features in a commutative diagram

$$\begin{CD} S_\partial^s(X \times I) @>{\textcircled{4}}>> [\Sigma(X_+), G/O]_* @>{\textcircled{6}}>> [\Sigma(X_+), BO]_* \\ @VV{\textcircled{8}}V @VVV @VVV \\ S^s(X \times S^1) @>>> [(X \times S^1)_+, G/O]_* @>>> [(X \times S^1)_+, BO]_* \end{CD}$$

whose middle and right vertical map are split injective, using that the quotient  $(X \times S^1)_+ \rightarrow \Sigma(X_+)$  splits after suspension and that  $G/O$  and  $BO$  are loop spaces. By the description of ⑥ ◦ ④ from (c), it suffices to show that any equivalence  $W \rightarrow X \times S^1$  from a closed smooth 5-manifold preserves the stable tangent bundle. This follows from the proof of [14, Theorem 6.1] (the statement assumes that the fundamental group is free abelian, but the proof goes through for  $\pi_1(X \times S^1) \cong \mathbf{Z} \times F_n$  since the version of the Novikov conjecture proved in [3, Theorem 7] applies).

Since ⑥ ◦ ④ is trivial, it follows from (f) and the fact that  $H^3(X; \mathbf{Z}) \cong H_1(X; \mathbf{Z}) \cong \mathbf{Z}^n$  is torsion free that ④ lands in the 2-torsion subgroup of  $[\Sigma(X_+), G/O]_*$  which is isomorphic to  $H^1(X; \mathbf{Z}/2)$ . By exactness of the upper row in (1) and injectivity of ④, in order to show that ① is surjective it suffices to prove that (④ ◦ ①):  $\pi_0 \text{hAut}_\partial^s(X \times I) \rightarrow [\Sigma(X_+), G/O]_*$  surjects onto the 2-torsion subgroup of  $[\Sigma(X_+), G/O]_*$ . This follows from constructing homotopy equivalences as in [15, p. 349–350]: first one shows that the Hurewicz homomorphism  $\pi_3(X) \rightarrow H_3(X) \cong \mathbf{Z}^n$  is surjective, which can be done as in the proof of Lemma 6.2 loc.cit. using the 1-truncation  $X \rightarrow B(F_n) \simeq \nu_n S^1$ , then one chooses a basis  $(\beta_i)$  for  $H_3(X)$ , lifts each  $\beta_i$  to  $\pi_3(X)$  and use the lifts to construct elements  $h_i \in \pi_0 \text{hAut}_\partial^s(X \times I)$  analogous to the construction of  $h$  on the top of p. 350 loc.cit. Since ④ is injective, if a sum  $\sum_i \varepsilon_i h_i \in \pi_0 \text{hAut}_\partial^s(X \times I)$  with  $\varepsilon_i \in \{0, 1\}$  not all zero were in the kernel of ④ ◦ ①, then its image under ⑧ would be homotopic to a diffeomorphism. But the argument on p. 350 loc.cit. shows that this is not the case, so the images of the  $h_i$  in  $[\Sigma(X_+), G/O]_* \cong H^1(X; \mathbf{Z}/2)$  are linearly independent and hence ④ ◦ ① is surjective for dimension reasons.

**Remark.** Theorem B was proved for *closed* manifolds, but it does not seem unreasonable that the proof extends to allow nonempty boundary. For the boundary connected sums  $Y_g := \sharp^g(S^1 \times D^3)$  with  $g \geq 0$  the statement can in fact be *deduced* from the closed case by a trick:

Given a diffeomorphism  $\phi: Y_g \rightarrow Y_g$  that fixes  $\partial Y_g$  and is homotopic to  $\text{id}_{Y_g}$ , we will show that  $\phi$  is also pseudoisotopic to  $\text{id}_{Y_g}$  relative to  $\partial Y_g$ . Extending  $\phi$  by the identity on the second copy of  $Y_g$  in its double  $D(Y_g) := Y_g \cup_{\partial} \bar{Y}_g \cong \sharp^g(S^1 \times S^3)$ , we obtain a diffeomorphism  $(\phi \cup \text{id}): D(Y_g) \rightarrow D(Y_g)$  that is homotopic to the identity. As  $\pi_1(D(Y_g)) \cong F_g$ , Theorem B ensures the existence of a pseudoisotopy  $H$  from  $(\phi \cup \text{id})$  to  $\text{id}_{D(Y_g)}$ . Restricting  $H$  to  $\bar{Y}_g$  gives a concordance embedding  $H|_{I \times \bar{Y}_g}$  from  $\bar{Y}_g$  into  $D(X)$ , and by isotopy extension it suffices to show that  $H|_{I \times \bar{Y}_g}$  is isotopic, as a concordance embedding, to the inclusion  $I \times \bar{Y}_g \subset I \times D(Y_g)$ . As  $\bar{Y}_g \subset D(Y_g)^{\text{g}}$  has handle codimension  $\geq 3$ , this holds by [6, Theorem 2.1, Addendum 2.1.2].

### Acknowledgements

We are grateful to Oscar Randal-Williams for pointing out an oversight in an earlier version.

## Declaration of interests

The authors do not work for, advise, own shares in, or receive funds from any organization that could benefit from this article, and have declared no affiliations other than their research organizations.

## References

- [1] A. Bak, “Odd dimension surgery groups of odd torsion groups vanish”, *Topology* **14** (1975), no. 4, pp. 367–374.
- [2] S. Cappell, “A splitting theorem for manifolds and surgery groups”, *Bull. Am. Math. Soc.* **77** (1971), pp. 281–286.
- [3] F. T. Farrell and W. C. Hsiang, “Manifolds with  $\pi_i = G \times \alpha T$ ”, *Am. J. Math.* **95** (1973), pp. 813–848.
- [4] D. Gabai, “3-Spheres in the 4-Sphere and Pseudo-Isotopies of  $S^1 \times S^3$ ”, 2022. <https://arxiv.org/abs/2212.02004>.
- [5] I. Hambleton and L. R. Taylor, “A guide to the calculation of the surgery obstruction groups for finite groups”, in *Surveys on surgery theory*, Princeton University Press, 2000, pp. 225–274.
- [6] J. F. P. Hudson, “Concordance, isotopy, and diffeotopy”, *Ann. Math.* **91** (1970), pp. 425–448.
- [7] M. A. Kervaire, “Smooth homology spheres and their fundamental groups”, *Trans. Am. Math. Soc.* **144** (1969), pp. 67–72.
- [8] R. C. Kirby and L. C. Siebenmann, *Foundational essays on topological manifolds, smoothings, and triangulations*, Princeton University Press, 1977, pp. vii+355.
- [9] R. C. Kirby and L. R. Taylor, “A survey of 4-manifolds through the eyes of surgery”, in *Surveys on surgery theory, Vol. 2*, Princeton University Press, 2001, pp. 387–421.
- [10] M. Kreck, “Isotopy classes of diffeomorphisms of  $(k - 1)$ -connected almost-parallelizable  $2k$ -manifolds”, in *Algebraic topology, Aarhus 1978 (Proc. Sympos., Univ. Aarhus, Aarhus, 1978)*, Springer, 1979, pp. 643–663.
- [11] J. Milnor, “A procedure for killing homotopy groups of differentiable manifolds”, in *Proc. Sympos. Pure Math., Vol. III*, American Mathematical Society, 1961, pp. 39–55.
- [12] F. Quinn, “The stable topology of 4-manifolds”, *Topology Appl.* **15** (1983), no. 1, pp. 71–77.
- [13] F. Quinn, “Isotopy of 4-manifolds”, *J. Differ. Geom.* **24** (1986), no. 3, pp. 343–372.
- [14] J. L. Shaneson, “Wall’s surgery obstruction groups for  $G \times Z$ ”, *Ann. Math.* **90** (1969), pp. 296–334.
- [15] J. L. Shaneson, “Non-simply-connected surgery and some results in low dimensional topology”, *Comment. Math. Helv.* **45** (1970), pp. 333–352.
- [16] R. Stong and Z. Wang, “Self-homeomorphisms of 4-manifolds with fundamental group  $Z$ ”, *Topology Appl.* **106** (2000), no. 1, pp. 49–56.
- [17] C. T. C. Wall, *Surgery on compact manifolds*, Second edition, American Mathematical Society, 1999, pp. xvi+302. Edited and with a foreword by A. A. Ranicki.